

TECHNICAL INSTRUCTIONS

29.7050 SURVEY CAMP

BATHURST, DECEMBER 1986

THE UNIVERSITY OF NEW SOUTH WALES

SCHOOL OF SURVEYING

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Technical Instructions

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I. GENERAL

1. SURVEY PROJECTS

The survey projects - triangulation, trigonometric levelling, ground control for photogrammetry, land use survey and cadastral survey - have been chosen so that the work involved will consolidate the third year class material. At the same time, the projects serve to introduce the fourth year. The technical programme can be completed well within the times allocated, providing the weather is suitable.

2. ORGANISATION

2.1 Computation Days

Computation days have been interspersed between the actual field days in order to provide sufficient time to process the field measurements at the camp site. These days should be utilised for this purpose only.

2.2 Use of Equipment

In order to make maximum use of the equipment and the time available, the class will be divided into groups of three. A work schedule is attached which should be strictly adhered to. However, should a group complete a project early, then it may commence work on any other project if the necessary equipment is available.

2.3 Use of Computing Facilities

Four NEC computers and software packages will be available at camp. Printers will also be available. You will be encouraged to write your own programmes for the reduction of your work. The following programmes are available:

Name	Description
Wordstar	The famous editor/word processor.
SOLVARM	Solution of parametric equations.
EDMRED	EDM reductions - first velocity, slope, sea level and ISG corrections.
SGLPNT	Single point determination using Least Squares. (Dirns, Dists, Azims).
COORDCNU	Coordinate conversions between geographicals, ISG and AMG.
MBD	Missing bearing and distance (Close).
RESECT	3 ray resection.
TRAVBA	Traverse adjustment by BOWDITCH.

2.4 Use of Vehicles

Students will NOT use private vehicles on private property, except with the express permission of a supervisor and the owner of the land in question.

3. PROJECTIONS

Two distinct projections will be used in the calculations. These are the Australian Map Grid (AMG) and the Integrated Survey Grid (ISG) systems. The ISG system should be adopted for all projects except the triangulation survey, where the AMG system shall be chosen. Both projections refer to the Australian National Spheroid ($a = 6378160m$ and $f = 1:298.25$). The elevations are on Australian Height Datum (AHD).

4. SUBMISSIONS

4.1 Report

Separate reports on each of the survey projects performed at camp shall be submitted by the due dates given in Sec. I-7.3. These reports are to contain the following:

- (a) an index page;
- (b) a summary of results;
- (c) an abstract of all field measurements;
- (d) reductions, calculations and adjustments;
- (e) explanatory remarks to clarify procedures adopted; and
- (f) appropriate cross-referencing where data used in one project is derived in another part.

4.2 Field Notes

The field notes and field books shall also be submitted.

4.3 Deadlines

The deadlines for submissions to the Technical Director will be 2300 hours on the dates specified. An extension of time WILL NOT be granted under any circumstances.

5. DATA

5.1 Projections

QUANTITY	AMG	ISG
Zone Width	6	2
Zone Number	55	55/3
Central Meridian	147 E	149 E
Scale Factor (k_0)	0.9996	0.99994
False Origin - East	-500 000 m	-300 000 m
- North	-10 000 000 m	-5 000 000 m

5.2 Formulae

E' = true Easting
 N' = true Northing
 k_0 = central scale factor
 ρv = product of both principal radii
 S = projection dista
 s = spheroidal distance

5.2.1 Arc-to-chord

$$\delta_{1-2} = \frac{(N'_1 - N'_2) (2E'_1 + E'_2)}{6 k_0^2 \rho v \sin 1''} \quad [\text{in arc seconds}]$$

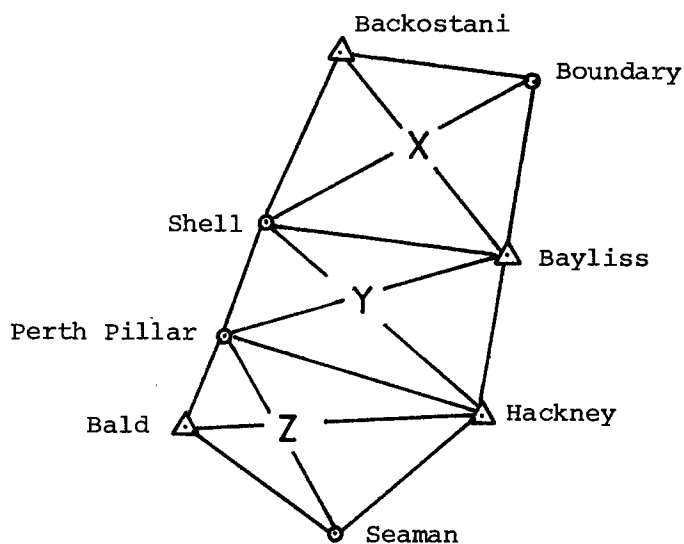
5.2.2 Scale factor

$$\frac{S}{s} = k \left[1 + \frac{E_1'^2 + E_1' E_2' + E_2'^2}{6 k_0^2 \rho v} \right]$$

5.2.3

$$\frac{10^8}{\rho v \sin 1''} = 0.5083754$$

5.3 Triangulation



Scheme

X : Perth-Pillar, Hackney, Seaman, Bald
 Y : Shell, Bayliss, Hackney, Perth Pillar
 Z : Backostani, Boundary, Bayliss, Shell

\triangle Coordinates given

\circ Coordinates to be determined

5.4 Coordinates and Elevations

5.4.1 AMG

POINT	E (m)	N (m)	HT (m)
Bayliss	740 300.49	6 294 601.30	716.85
Hackney	740 218.93	6 292 453.65	-
Bald	735 930.76	6 292 379.23	851.63
Backostani	738 677.78	6 297 777.46	-

5.4.2 Coordinates in ISG 55/3 system, elevations on AHD

STATION NO.	STATION NAME	EASTING	NORTHING	ELEVATION
90	Red Hill	333 166.56	1 291 080.33	
91	Mulley (CMA)	352 623.70	1 299 490.10	731.76(Top pillar)
92	Durham Court Pillar	361 005.51	1 299 149.74	768.07(Top pillar)
93	Baanya Pillar	350 940.80	1 301 958.80	731.82(Top pillar)
94	Avondale Pillar	350 502.00	1 307 950.10	723.52(Top pillar)
95	Clarke	330 143.97	1 283 996.21	
96	Macquarie	316 673.11	1 275 602.25	
97	Errol	322 236.56	1 284 793.46	
98	Crackersack	338 149.77	1 304 547.17	
99	Edrop	344 963.09	1 309 186.82	
100	Rankin	347 444.18	1 312 180.98	
101	Lowes Pillar	375 182.00	1 281 532.89	1 133.52(Top pillar)
102	Ovens Pillar	372 099.23	1 301 416.35	1 273.90(Top pillar)
103	Rocks Pillar	337 609.29	1 298 393.38	1 038.45(Top pillar)
104	Bald	350 107.74	1 293 874.29	851.63
105	Bayliss	354 432.44	1 296 179.34	716.85
106	El Woodara	342 929.60	1 299 282.28	
107	Cherry Tree	349 031.23	1 299 106.63	827.96
108	Evernden Pillar	350 451.01	1 284 884.82	990.5*
110	Hackney	354 392.26	1 294 031.23	753.0*
112	Hollis	351 552.61	1 290 745.47	787.97
113	Humby	350 537.41	1 299 155.91	788.0*
114	Lenehan	347 131.77	1 292 057.34	812.88
115	Boundary	354 869.26	1 298 610.71	680.5*
117	Shell	351 143.71	1 296 558.49	873.5*
118	Peel	363 578.74	1 307 341.58	878.18
120	Seaman	352 176.26	1 292 479.96	734.5*
121	St. Stanislaus	353 015.28	1 299 583.33	738.36 (see sketch)
122	Three Brothers	336 080.31	1 275 516.46	
124	Williams	348 604.89	1 292 964.50	795.37
126	Panorama	350 822.85	1 297 238.54	874.02(Top pillar)
127	Perth-Pillar	350 579.52	1 295 238.07	879.5*
128	Rutherford	355 518.02	1 303 906.86	701.98
131	Lee Pillar	358 911.85	1 300 003.49	740.00
134	Bushranger Pillar	344 729.91	1 292 362.33	865.37(Top pillar)

135	Oakleigh Pillar	358 450.04	1 303 347.43	771.23(Top pillar)
136	Tareen Pillar	358 673.00	1 297 009.00	754.46(Top pillar)
137	Hackney Pillar	354 784.60	1 294 999.64	741.08(Top pillar)
138	Gormans Hill Pillar	354 945.01	1 298 271.82	687.75(Top pillar)
139	SSM2234	351 784.39	1 296 552.98	
140	Cadastral	352 354.25	1 296 421.39	
141	Cadastral 2	352 670.40	1 296 333.52	
143	Tarella Pillar	359 894.80	1 315 005.36	
150	Carrawarra	354 088.39	1 305 469.67	
151	Carto School (TAFE)	352 495.86	1 299 096.42	710.57
152	Backostani	352 749.45	1 299 322.53	717.52

* Rounded to the nearest 0.5m. If higher accuracy is needed, use your own data determined in the trigonometric levelling project.

6. ORGANISATION OF TECHNICAL PROGRAMMES

6.1 Projects and Supervisors

IDENT.	PROJECT	DAYS ALLOCATED	WEEK	SUPERVISOR
1	Reconnaissance and Briefing	1/2	1	Dr. A.H.W. Kearsley
2	Triangulation and Trig. Levelling	2	1 2	Dr. A.H.W. Kearsley Dr. J.M. Rueger
3	Ground Control for Aerial Mapping	2	1 2	Prof. J.C. Trinder Mr. S. Ganeshan
4.	Cadastral Survey	2	1 2	Mr. S. Bennett/Prof. B. Forster Dr. B. Harvey
5.	Land Use Survey	2	1 2	A/Prof. B. Forster Mr. P.S. Amin
6.	Computations			Individual Supervisors

6.2 Directors

Administrative Directors - Professor J.C. Trinder and
Mr. S. Ganeshan

Technical Director - Mr. P.S. Amin

6.3 Storeman

Mr. A. Stevens

7. WORK SCHEDULE

7.1 Timetable

GROUP	MON 8	TUE 9	WED 10	THU 11	FRI 12	SAT 13	SUN 14	MON* 15	TUE 16	WED 17	THU 18	FRI 19
1	1	2x	2x	C	5	3	3	C	4	4	C	
2	1	2x	2x	C	5	3	3	C	4	4	C	
3	1	2z	2z	C	5	3	3	C	4	4	C	
4	1	2z	2z	C	5	3	3	C	4	4	C	
5	1	3	3	2x	2x	C	4	C	4	5	C	
6	1	3	3	2x	2x	C	4	C	4	5	C	
7	1	3	3	2z	2z	C	4	C	4	5	C	
8	1	3	3	2z	2z	C	4	C	4	5	C	
9	1	4	4	C	5	2x	2x	C	3	3	C	
10	1	4	4	C	5	2x	2x	C	3	3	C	
11	1	4	4	C	5	2z	2z	C	3	3	C	
12	1	4	4	C	5	2z	2z	C	3	3	C	
13	1	5	3	3	4	4	C	2x	2x	C	C	
14	1	5	3	3	4	4	C	2x	2x	C	C	
15	1	5	4	4	3	3	C	2z	2z	C	C	
16	1	5	4	4	3	3	C	2z	2z	C	C	

7.2 Task

1. Travel to Bathurst, Briefing, Reconnaissance.
2. Trig. & Trig. Levelling: 2x - Area X, 2Y - Area Y, 2z - Area Z.
3. Ground Control for Aerial Surveying.
4. Cadastral Surveying.
5. Land Use Survey.
- C. Computations.
- * Visit C.M.A. (a.m.)
- + Social Occasion (p.m.)

7.3 Submission: Before 11 p.m. on the day indicated below.

- | | |
|-------------------|--------------|
| 1. Reconnaissance | same day |
| 2. Triangulation | plus one day |
| 3. Ground Control | plus one day |
| 4. Cadastral | plus one day |
| 5. Land Use | same day |

II. PROJECTS

1. RECONNAISSANCE

This exercise will involve a familiarisation of the camp area and surrounding control network, erection or dismantling of beacons, and the preparation of access and recovery sketches. (See Appendix A). These sketches will be displayed for the use of parties involved in Projects 2 and 3. Two eccentric stations, one due North (AMG) and another one due East (AMG), each 10.0m from the trigonometric station should be placed during reconnaissance. (They will be used to check the plumbing of the beacon during each occupation of the station.)

Details will be discussed during the briefing session, which is to be given at 1.00 p.m. on the day of arrival at the camp.

1.1 Equipment

- 1 Compass
- 1 x 2 m folding ruler
- 1 x 100m steel band
- 1 x 3m pocket tape
- 1 x 30m steel tape
- 1 x one second Theodolite + Tripod
- 1 Plumbob with 3 m string
- 2 x dumpy pegs
- 1 Binoculars
- 1 pocket calculator

2. TRIANGULATION AND TRIGONOMETRIC LEVELLING

2.1 Equipment

- 1 x one second Theodolite + Tripod
- 1 Plumbob with 3m string
- 1 x 30m Tape
- 2 Umbrellas with steel base
- 1 Hammer
- 1 x 2m folding ruler
- 1 x 3m pocket tape
- 3x dumpy pegs

2.2 Project

2.2.1 Triangulation

The aim of the exercise is to determine the AMG coordinates of 2 stations and the A.H.D. heights of 3 stations in a braced quadrilateral based on coordinates and heights given in Section I-5.4.1.

On all four stations of the quadrilateral, two group members shall each measure three arcs of horizontal directions to the stations of the braced quadrilateral which is specified in the network schedule.

Before commencing the daily observations and before leaving the site, all the signals must be checked for verticality, measured for eccentricity and replumbed if necessary.

At each station, the station adjustment is carried out in the field by computing the reduced means, the grand mean, the standard deviation of a single observation (in 2 faces) and of the grand mean directions.

The standard deviation of a direction in the grand mean shall be less than or equal to ± 0.8 second of arc. If required, additional arcs should be observed until the above specification is met.

On completion of the field work, the observations will be corrected for arc-to-chord (AMG) and any eccentricities of the beacons at the target stations. Groups shall compute the four triangle misclosures and derive the standard deviation of a (grand mean) direction from the FERRERO equation, where the ε are the triangle misclosures and n is the number of triangles.

$$\sigma_{DIR} = \pm (\sum \varepsilon^2 / 6n)^{0.5}$$

Observations will then be adjusted by the "parametric" method to give corrections to the observations, the station coordinates (AMG) and the error ellipses.

The variance of the observations is given by:

$$\sigma^2 = (\sigma_{GM}^2 + \frac{0.206265^2}{s^2} (\sigma_I^2 + \sigma_T^2)) \quad (\text{sec}^2)$$

where σ_{GM}^2 = standard deviation of grand mean of arc concerned

σ_I^2 = standard deviation of centring at instrument station (in millimetre)

σ_T^2 = standard deviation of centring of beacon (in millimetre)

s = distance between instrument and target stations (in kilometre)

The observation equations and other details of the adjustment are given in the Appendix B.

Field notes should conform with the example shown in Appendix B.6 Special booking forms will be supplied.

2.2.2 Trigonometric levelling

On all four stations of the quadrilateral, two group members shall each measure two arcs each of zenith angles by the Three-Hair-Method to the other stations of the braced quadrilateral. These observations should be carried out between 10.00h and 16.00h (summer time). The measurement of height of instrument and beacons is important.

Special booking forms for the 3-Hair-Method will be provided. The meteorological conditions at the time of measurement shall be recorded (cloudiness, visibility, time, shadow/sun, wind). At each station and for each line, the standard deviation of a single zenith angle observation and of the mean of 12 zenith angles (four observations by 3-hair-method) shall be computed.

The individual height differences are to be calculated using the following formula (dimensions are in metres):

$$\Delta H = s \left(1 + \frac{H}{R} \left[\cot Z + \frac{(1-k)s}{2R} \right] \right) + (HI - MT)$$

where

Δh is the height difference;
 s is the spheroidal distance;
 H is the altitude of observation station;
 R is the radius of spheroidal section (6370 100m for this project);
 Z is the observed zenith angle;
 k is the refraction coefficient (assume +0.14 for this project);
 HI is the height of instrument; and
 HT is the height of target.

The spheroidal distance s should be computed from the given I.S.G. coordinates (see I-5.4.2) and NOT from AMG coordinates.

The field work should be checked by computing the four triangle misclosures from the mean height differences of each line and by deriving an overall standard deviation for mean height differences from:

$$\sigma_{\Delta h} = \sqrt{\frac{\sum \epsilon^2}{3n}}$$

where the ϵ are triangular misclosures (in centimetre) and n is the number of misclosures (four in this case).

The mean height difference for each line will then be entered into a least squares adjustment to produce the adjusted heights of the stations. The variance of a mean height difference from reciprocal observations should be estimated by the formula:

$$s_{\Delta h}^2 = 0.24 s^2 (s_z^2 + 450 s^2 s_k^2)$$

where

s_{Δ}^2 is the variance of the mean height difference in cm ;

s is the distance in km; and

s_z is the standard deviation of the grand mean of the zenith angle in seconds of arc (mean st. dev of forward and backward zenith angle).

s_k is the uncertainty of the coefficient of refraction k for non-simultaneous reciprocal trigonometric heighting. Use ± 0.03 in this exercise.

Note: Above equation is based on the assumption that the standard deviations of height of instrument and height of beacon are in the millimetre range and, thus ineffective.

2.3 Submission

Each group shall submit for assessment the field notes, the calculations and a report on the project, including a discussion of the achieved precision.

The submissions for the project are to be prepared in accordance with Section I-4 of these instructions.

3. GROUND CONTROL FOR PHOTOGRAMMETRY

3.1 Equipment

1 x 1"	Theodolite + Tripod
1	100m Steel band + Spring Balance + Thermometer
1	EDM instrument + Ancillary equipment (when available)
1	Pair of photographs
1	Pocket stereoscope

3.2 Ground Control

The task at camp will be to reconnoitre, identify and fix two ground control points whose approximate positions will be marked in the photograph by the supervisor. See Appendix C1 and C2 for examples of typical control points. The points should be fixed in plan and height with a precision of 0.10m or better, but separate plan and height controls may be chosen in each of the two locations if a suitable single point cannot be found.

At least one of the control points must be fixed by a closed (not loop) traverse. The other may be fixed by traverse, triangulation or resection. The calculation of the coordinates must include all observations that are made. Repeated arcs or repeated measurements of the same distance will not count as redundant observations. This means that there must be an independent geometric check for each point.

All trig. stations may be used for fixing the photo control.

3.3 Submissions

A single group report will be submitted including a reconnaissance sketch, photo point diagrams (see Appendix C2), computations and field notes.

4. CADASTRAL SURVEY OF CAMP BOUNDARY

4.1 Object

The purpose of the exercise is to redefine the boundaries for a Real Property Application of nominated land adjacent to Karingal Village. Information relating to procedures can be found in Appendix D.

4.2 Equipment

1 x 10" or 1'	Theodolite + Tripod
10	Roof Nails
1	100m Steel band + Spring balance + Thermometer
1	Short Range EDM instrument + Accessories (available 1 day only for selected lines)
2	Prisms + Tribrachs + Tripods (1 day only)
2	Sighting + Tripods + Plumbobs

Plus other necessary aids.

4.3 Survey

The method of survey will consist of a loop traverse around the boundaries together with connections to two of the listed controls. Cutting of scrub and timber is not permitted. Please take care not to break branches or stand on any seedlings, especially if working on the south side of the Campsite. Traverse lines must therefore be selected so as to be clear of all obstacles.

Details on survey techniques to be employed will be discussed at a briefing session prior to the commencement of the project.

4.4 Computations

The surround survey should be adjusted by an appropriate method. Reduced distances should be derived and shown on the plan of survey. The report on the project will contain a comparison between measured ground distances (reduced for slope) and distances shown on the relevant survey plans.

4.5 Submissions

Each group is required to submit field notes, calculations, a sketch plan of boundaries, and a brief report on the project. The sketch plan should be at appropriate scale and drawn on quality drafting paper and show boundary marks, reference marks, occupations, the traverse line, the final boundary bearings and distances. (See Appendix D).

5. LAND USE SURVEY

5.1 Purpose

The purpose of this exercise is for each group of students to carry out a land use survey of a selected area in the environs of Bathurst. Information relating to detailed procedures can be found in Appendix F.

5.2 Equipment

1 Pair of photographs
1 Mirror stereoscope
1 1:25 000 Map sheet
Tracing paper overlays

5.3 Survey

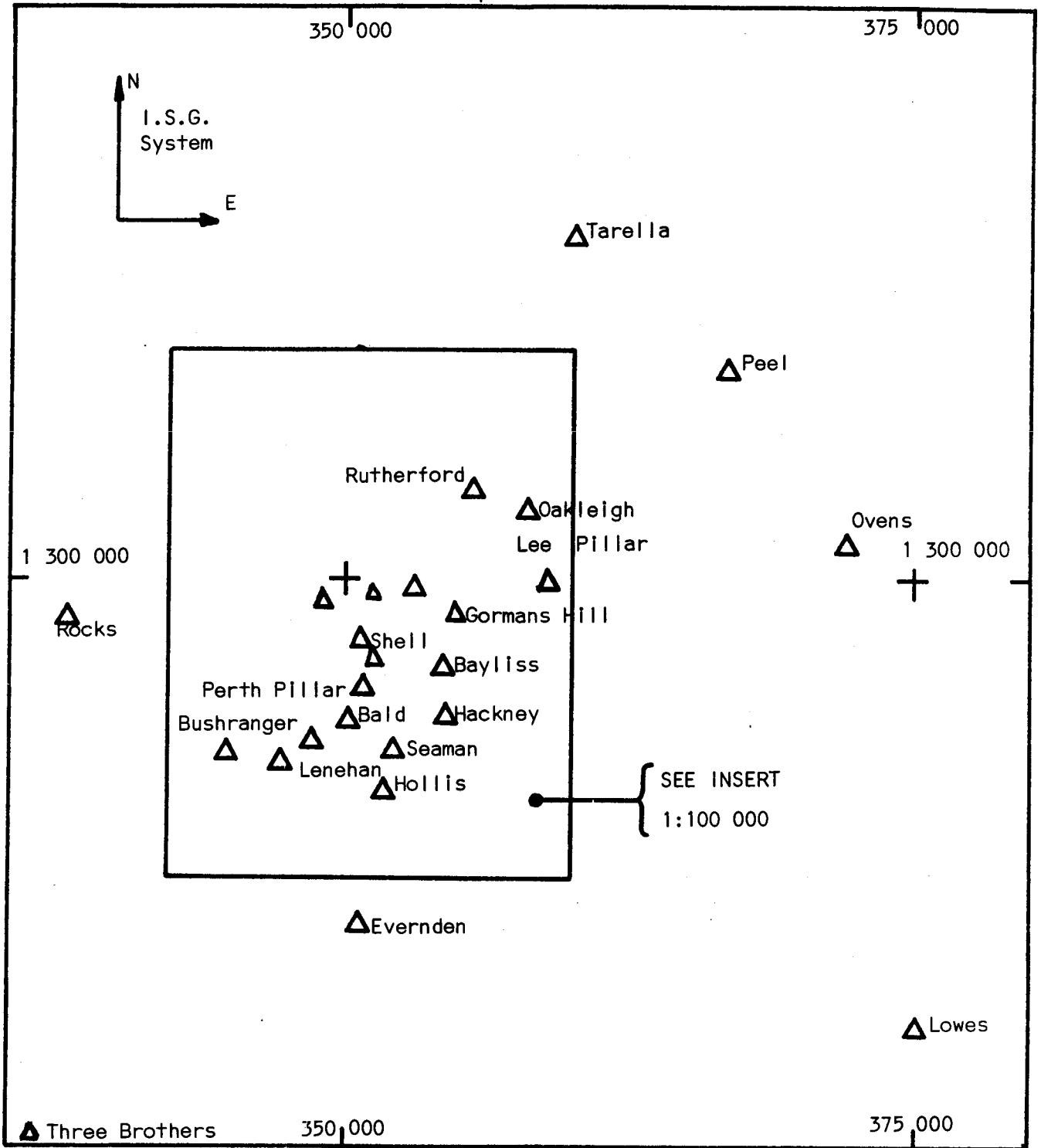
In making this survey, both field sampling and air photo interpretation techniques will be employed to produce a coded and symbolised land use map. The task will entail three distinct stages:

- (1) Air photograph selection of representative areas.
- (2) Ground inspection and interpretation of those selected areas.
- (3) Air photo interpretation based on ground inspected areas.

5.4 Submissions

Each group is required to submit photo overlay, field notes of site visits, coded land use map and a report.

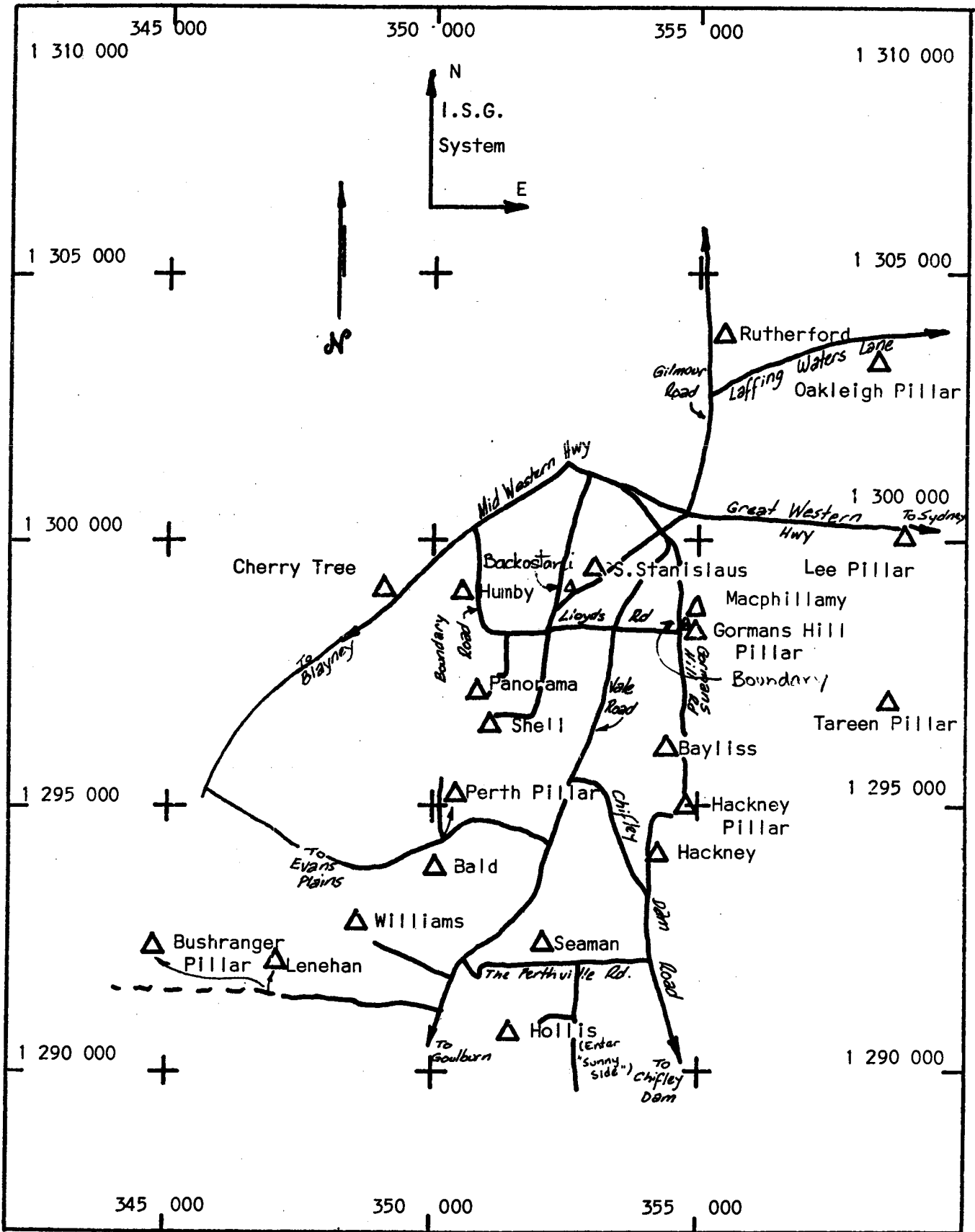
Appendix A.1



PLAN

SHOWING TRIG STATIONS IN THE BATHURST AREA.

SCALE: 1:250 000



INSERT

SHOWING TRIG STATIONS AND LOCAL ROAD SYSTEMS.

SCALE: 1:100 000

This Trig. Station has been:-

Note: Cross out word or words which do not apply

1. Completely cleared to permit 360° vision to surrounding Trigs.
2. Cleared by lanes bearing from Trig. Mast
3. Trig. Mast & Vanes have been painted white & black respectively.
4. The Trig. was unpiled/~~not unpiled~~, dimensions now being:
 - Description of mark. ~~Cone. Cairn. 6.445.~~ should be explicit, e.g. Steel plug, Brass plug, Bolt, G.I. Pipe
 - Height of mark. ~~0.222.~~ m ^{above} ~~below~~ rock/concrete ~~0.22~~ m ^{above} ~~below~~ G.L.
 - Height of Top Vanes to Top Mark. ~~3.444.~~ m. Diameter of Vanes (vertical) ~~0.216.~~ m.
 - Height of Cairn. ~~0.510.~~ m. Diameter of Cairn ~~2.2.~~ m.
 - Length of Mast ~~2.520.~~ m. (approximate if not unpiled)

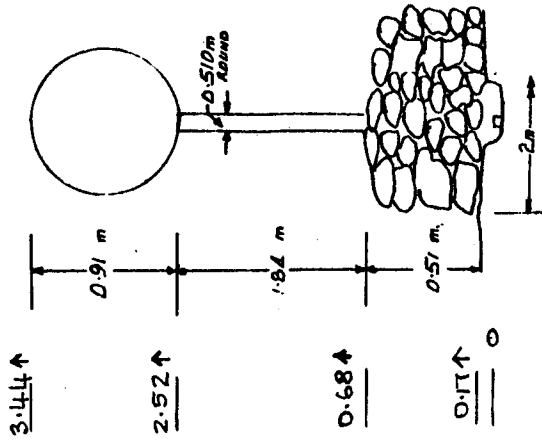
5. ~~A.C.M.A.~~ set in conc./~~rock~~ has been placed ~~2.600.~~ m. bearing ~~0 6.~~ °M from Trig. Mast
6. ~~A.G.I.Pipe.~~ set in conc. ~~soil~~ has been placed ~~2.065.~~ m. bearing ~~2 3.~~ °M from Trig. Mast
7. A. set in conc./soil has been placed m. bearing °M from Trig. Mast
8. A. set in conc./rock has been placed m. bearing °M from Trig. Mast
9. Connection ~~Plus.~~ to ~~G.I. Pipe.~~ : ~~2.600.~~ m. bearing ~~2 6 6.~~ °M
10. Connection ~~Plus.~~ to ~~G.I. Pipe.~~ : ~~2.665.~~ m. bearing ~~11 3.~~ °M
11. Connection. ~~S.I.P.~~ to ~~Cu Nail.~~ : ~~4.595.~~ m. bearing ~~2 7 9.~~ °M
12. Connection to : m. bearing °M
13. Diff. Ht. ~~Trig. Plus.~~ is ~~0.210.~~ m. ~~to~~ ~~Cu Nail.~~
14. Diff. Ht. ~~Trig. Plus.~~ is ~~0.190.~~ m. ~~to~~ ~~G.I. Pipe.~~
15. Diff. Ht. is m.
16. Diff. Ht. is m.

Prepared by: Checked:

Noted on U.T.M. Card 372

Checked

Beacon Diagram Not to Scale



Record of Station

Date	Record of Station

A.4/1

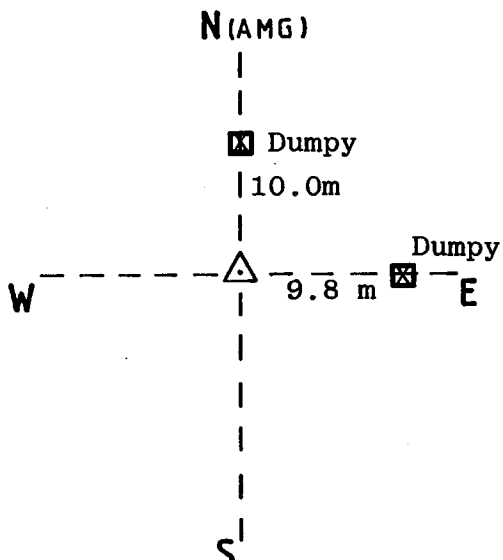
BEACON DIMENSIONS

STATION: HACKNEY
=====

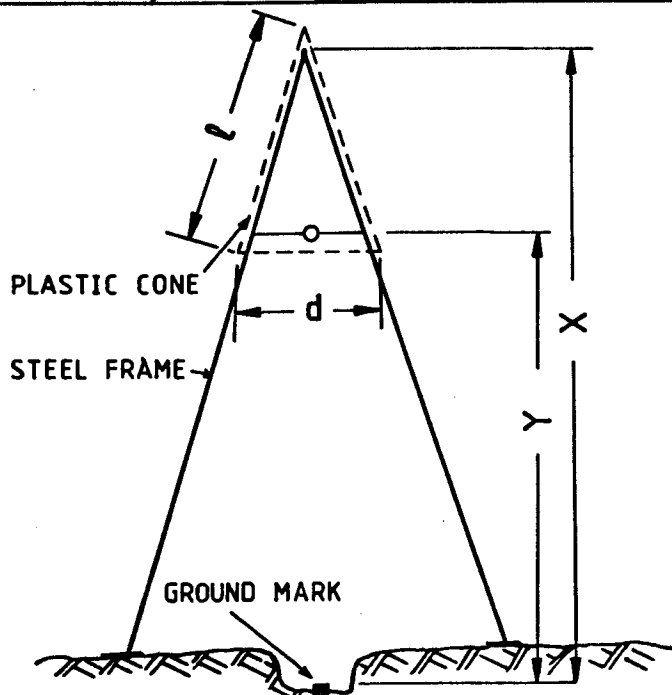
PLEASE MEASURE THE 4 DIMENSIONS (TO MILLIMETRE)

DATE	TIME	GROUP No:	X	Y	l	d
			mm	mm	mm	mm
3.12.84	15.00 h	1	3587	2985	870	830
5.12.84	14.00	5		2986		
6.12.84	16.30	9		2985		
7.12.84	13.38	12		2985		
8.12.84	14.36	12		2985		
9.12.84	17.00	3		2983		
7.12.84	9.00	8		2982		
10.12.84	6.25	13		2982		
10.12.84	11.30	13		2982		

SKETCH OF PLUMBING PEGS



Pegs by Group 1, 3.12.1984



A4/2

BEACON ECCENTRICITY

STATION:

PERTH PILLAR

=====

BOOK ECCENTRICITIES OF BEACON TOPS RELATIVE TO GROUND MARKS(or PILLAR) IN MILLIMETRE.

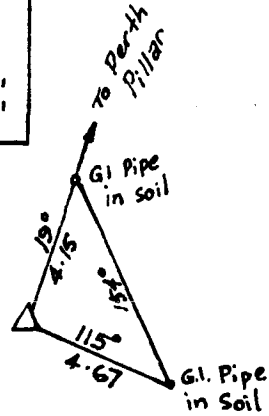
(e.g. 4.5 mm N = Top of Beacon is 4.5 mm North of ground mark.)

DATE	TIME	GROUP No	N/S mm	E/W mm	ENTERED BY:
30.11.83	09.30	15	0.0	0.8 E	
30.11.83	14.00	15	0.0	0.5 E	
1.12.83	10.40	16	6.0 N	2.0 W	
1.12.83	14.45	16	8.0 N	1.0 W	
1.12.83	08.00	13	6.0 N	1.0 W	
1.12.83	10.30	13	6.0 N	2.0 W	
1.12.83	15.00	14	8.0 N	1.0 W	
1.12.83	18.10	14	6.0 N	1.0 W	
3.12.83	14.00	17	7.0 N	0.0	
3.12.83	17.45	17	15.0 N	7.0 E	
4.12.83	14.00	3	16.0 N	0.0 E	
4.12.83	16.30	3	16.0 N	0.0 E	
5.12.83	13.00	4	18 N	14 E	
5.12.83	16.00	4	18 N	14 E	
6.12.83	16.00	7	16 N	15 E	
7.12.83	16.00	7	15 N	14 E	
8.12.83	15.00	11	11 N	12 E	
8.12.83	18.30	11	11 N	12 E	
9.12.83	16.00	12	15 N	13 E	
9.12.83	18.30	12	15 N	13 E	

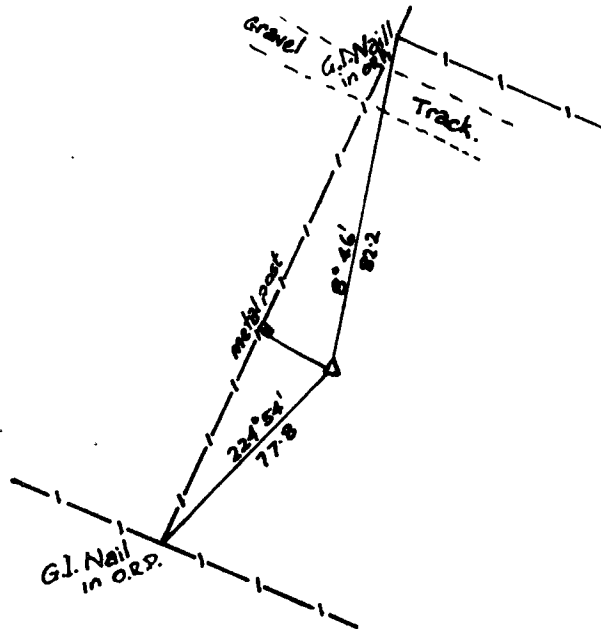
A.5

'BALD T.S.'

STATION	DIRN
Perth Pillar	19° 06'
Bayliss	61° 57'
Hackney	87° 54'
Seaman	123° 59'
Lenehan	238° 36'
Williams	238° 49'
Bushranger	254° 20'



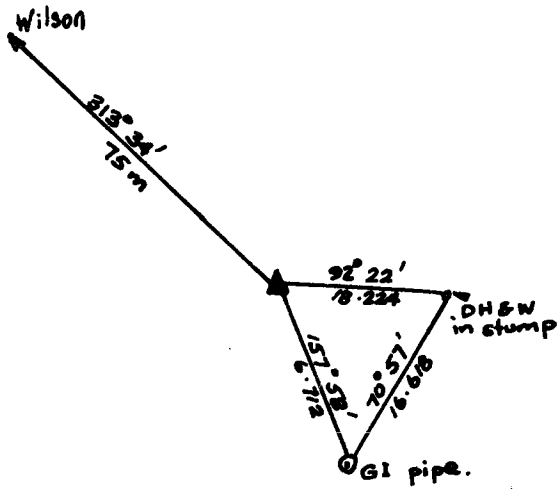
'BAYLISS T.S.'



STATION	DIRN
M ^c Phillammy	9° 33'
Hackney	181° 04'
Bald	241° 57'
Perth Pillar	256° 16'
Shell	276° 35'
Cherry Tree	298° 27'
Humby	307° 23'

A.6

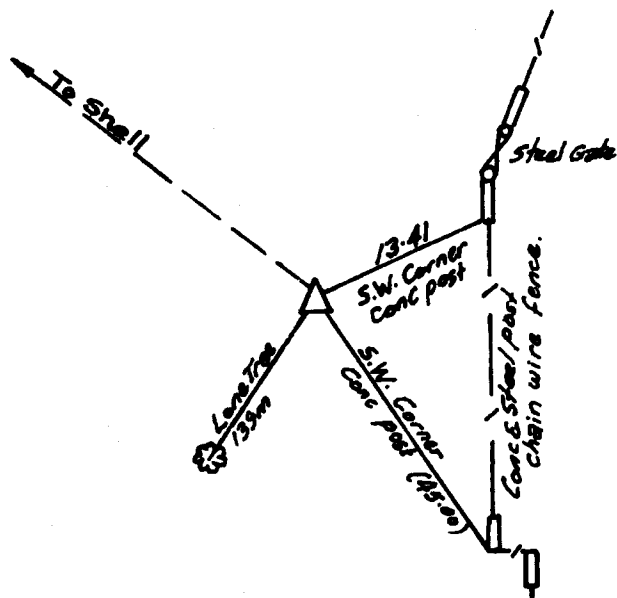
'CHERRY TREE T.S.'



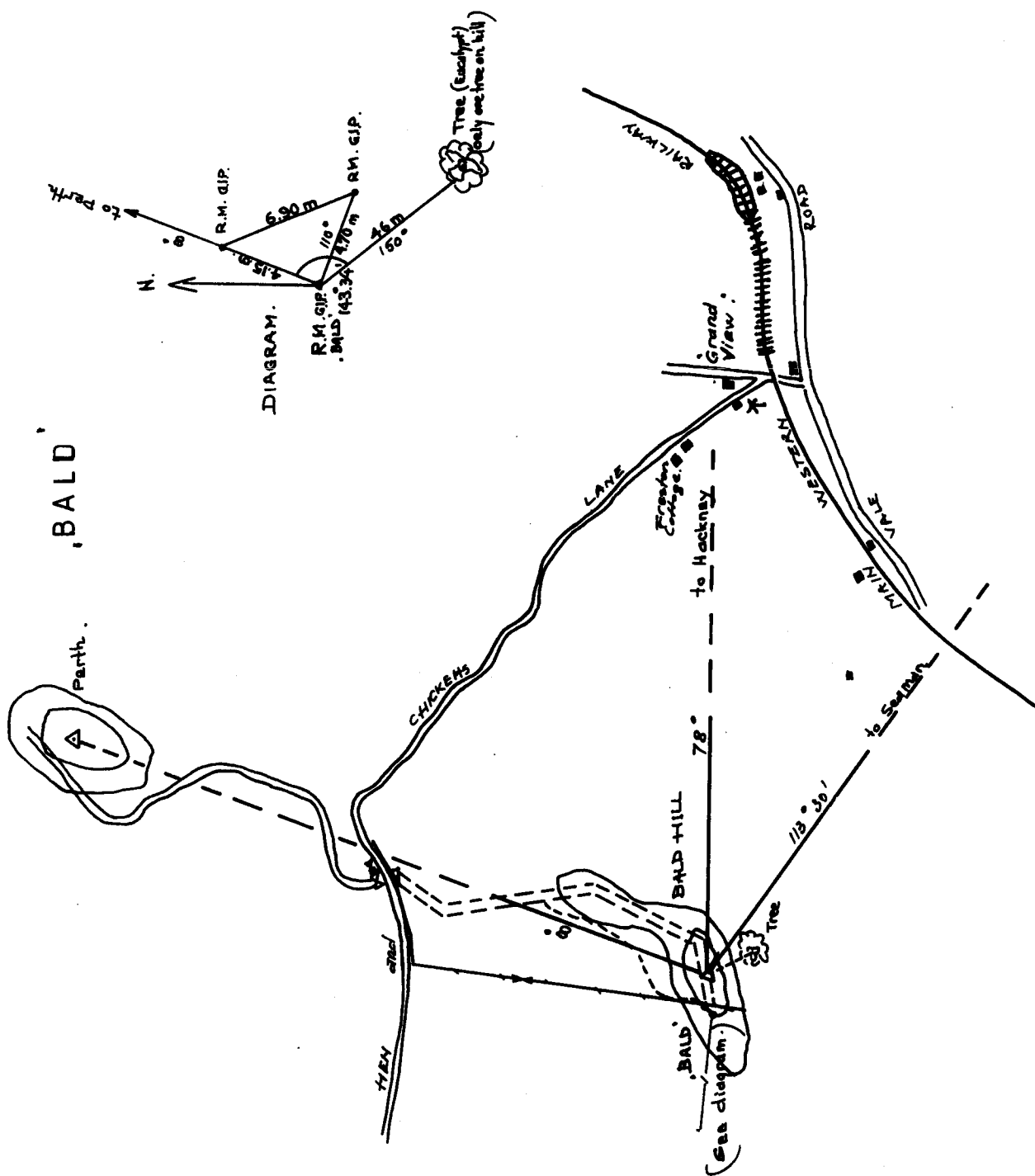
STATION	DIR N
Tarella	34° 20'
Peel	60° 29'
St Stanislaus	83° 11'
Humby	88° 08'
MacPhillamy	94° 51'
Baylies	118° 27'
Panorama	88°
Perth Pillar	158° 11'
Bald	168° 22'
Everden	174° 17'
Williams	183° 58'
Lenahan	195° 05'
Bushranger	212° 33'
Wilson	331° 34'

'HACKNEY T.S.'

STATION	DIR N
Shell Tower	0° 00'
St. Stanislaus	38° 10'
Baylies	53° 10'
MacPhillamy	57° 42'
Seaman	287° 04'
Williams	311° 36'
Bald	319° 57'
Perth	339° 37'



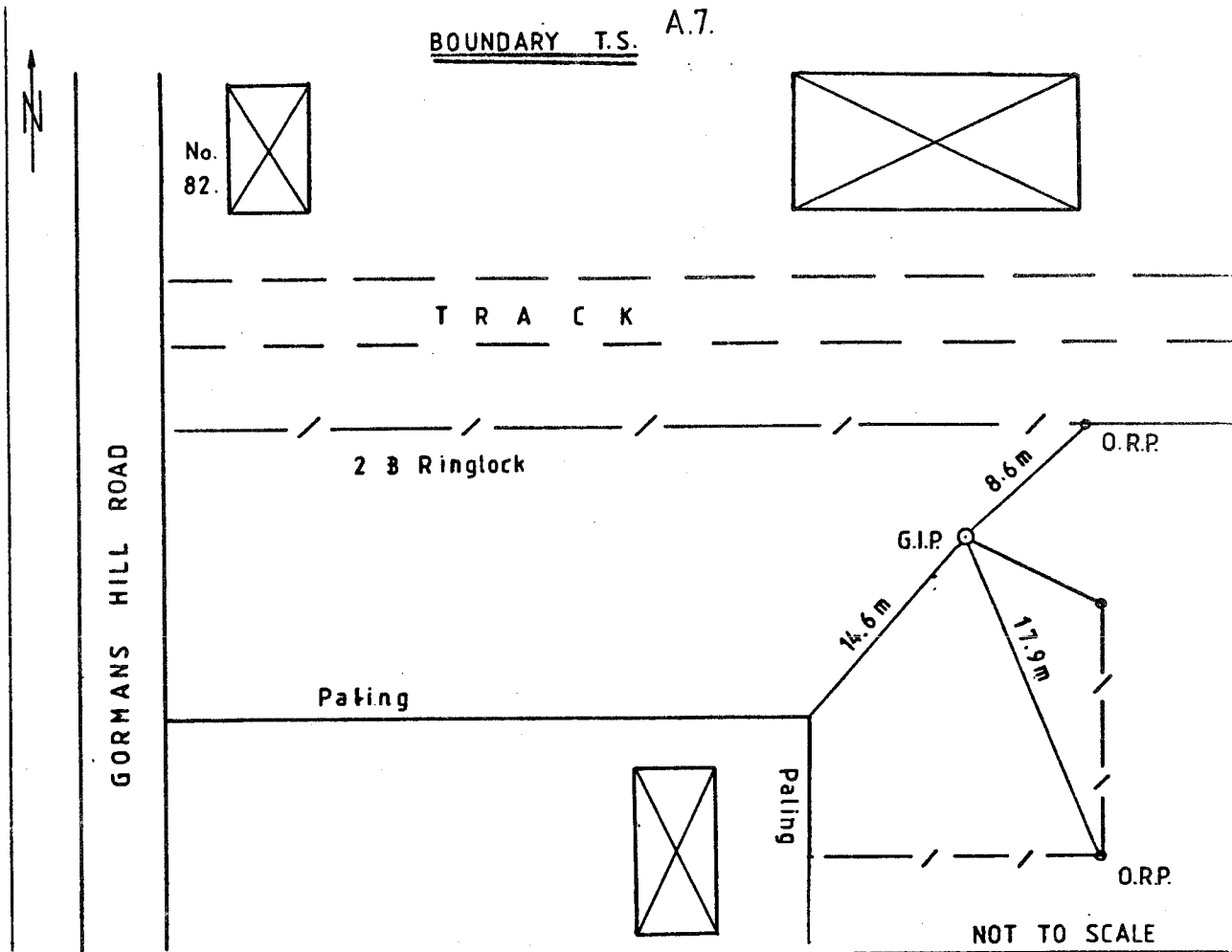
A 6/1



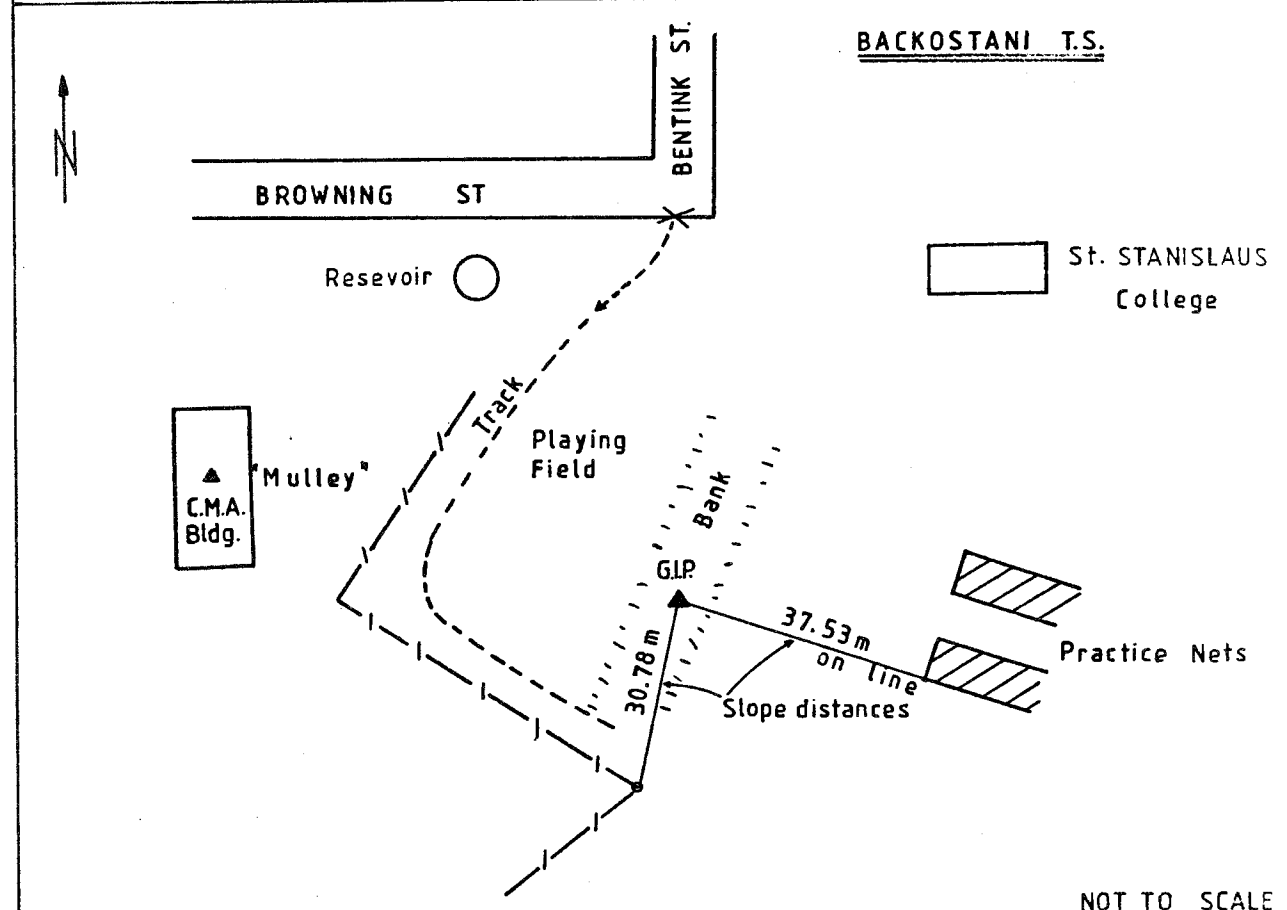
BATHURST

2 Oct. 1984
Drawing . C. Rusu

BOUNDARY T.S. A.7.

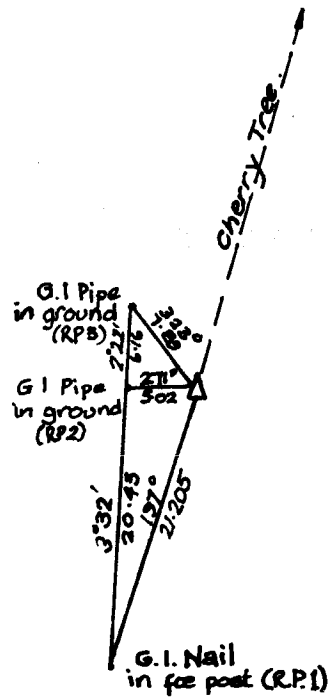


BACKOSTANI T.S.



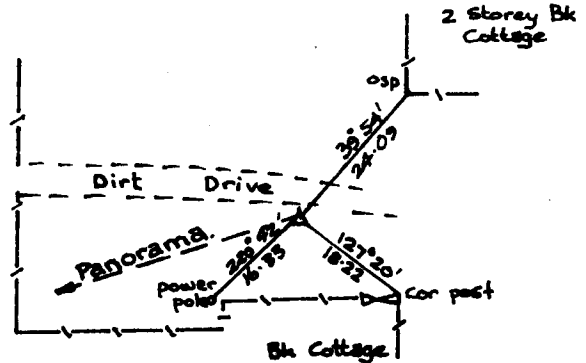
MARK: G.I.Pipe
(0.1 below surface)

A.8
'LENEHAN T.S.'



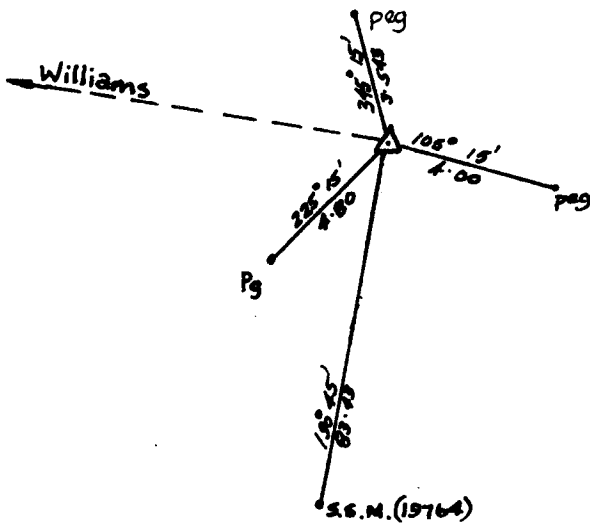
'M^cPHILLAMY T.S.'

STATION	DIR ⁿ
Cherry Tree	0°00'00"
Perth Pillar	32°13'
Bald	43°31'
Bushranger	262°11'

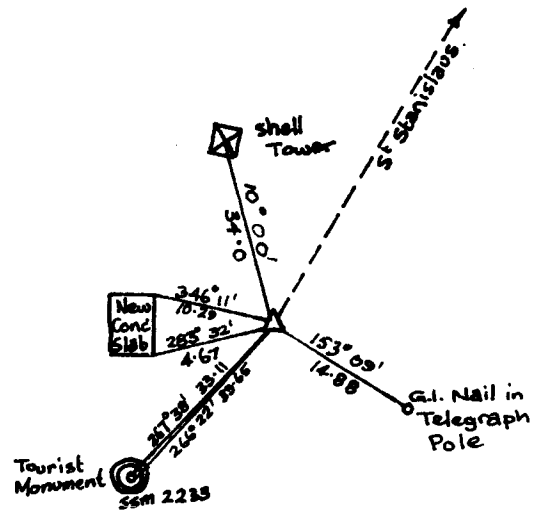


STATION	DIR ⁿ
Hackney	105°37'
Perth Pillar	231°37'
Shell	240°56'
Panorama	251°06'
Cherry Tree	274°51'
Humby	277°10'
S ^c Stanislaus	297°57'
Tarella	17°08'

' SEAMAN T.S. ' ^{A.9}



' SHELL T.S. '

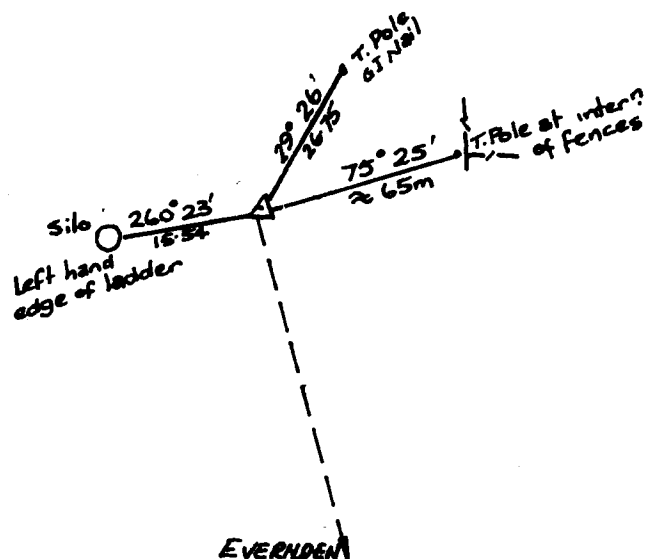


STATION	DIRN
Lenahan	$265^{\circ} 13'$
Williams	$277^{\circ} 44'$
Bald	$303^{\circ} 59'$
Perth	$329^{\circ} 56'$
Shell	$345^{\circ} 48'$
Hackney	$55^{\circ} 01'$
Three Brothers	$225^{\circ} 15'$

STATION	DIRN
Panorama	$334^{\circ} 45'$
Humby	$346^{\circ} 52'$
St Stanislaus	$31^{\circ} 45'$
M ^c Phillamy	$60^{\circ} 56'$
Bayliss	$96^{\circ} 35'$
Hackney	$127^{\circ} 53'$
Perth Pillar	$203^{\circ} 08'$

' WILLIAMS. T.S. '

STATION	DIRN
Evenden	$0^{\circ} 00'$
Three Brothers	$48^{\circ} 35'$
Lenahan	$71^{\circ} 16'$
Cherry Tree	$196^{\circ} 52'$
Perth Pillar	$283^{\circ} 52'$
Seaman	$290^{\circ} 37'$



A9/1

"SEAMAN"



BATHURST

Oct. 1984.
Drawing - C. RUSU.

Appendix B

COMPENDIUM OF FORMULAE
for the
LEAST SQUARES ADJUSTMENT
of
CONTROL NETWORKS
by the
VARIATION OF COORDINATES

1. NOTATION AND BACKGROUND

A set of n linearized observation equations is given by:

$$v = Bx + T$$

where v is the vector of residuals of the n observations p_i
 B is the matrix of coefficients b_{ij} (calculated from approximate values of parameters x),
 x is the vector of u independent parameters, and
 T is the vector of absolute terms.

The vector of absolute terms is calculated from

$$T = p^0 - p$$

where p is the vector of observed values, and
 p^0 is the vector of constant terms, calculated from approximate values of parameters x .

The number of redundancies, r , is given by

$$r = n - u$$

The population variance σ_i^2 of each observation p_i can be expressed by a variance estimator S_i^2 :

$$S_i^2 = S^2 \cdot g_{ii} ,$$

where S^2 is the a priori (dimensionless) variance factor, and
 g_{ii} is the weight coefficient of the particular observation.

The weight coefficients g_{ii} form a matrix G , which is a diagonal matrix for the case of uncorrelated observations.

2. SOLUTION

The most probable values for the parameters x are found according to the Principle of Least Squares by minimizing the quadratic form M by variation of the parameters.

$$M = v^T G^{-1} v = \left[\frac{vv}{g} \right]$$

This minimization leads to the normal equation system:

$$N x + C = 0 ,$$

which can be solved by suitable methods. The matrix of normal equation coefficients N and vector of constant terms C are given by:

$$N = B^T G^{-1} B$$

$$C = B^T G^{-1} T$$

The solution for the parameters is found by

$$\begin{aligned} \Delta X &= -N^{-1} B^T G^{-1} T \\ &= -N^{-1} C. \end{aligned}$$

Values of final parameters x are calculated from

$$x = \bar{x} + \Delta x.$$

3. CHECK CALCULATIONS

Values for the adjusted observations p_i are calculated from the final parameters x . Hence the residuals are found as the difference between p_i^a and the original observations p_i :

$$v_i = p_i^a - p_i \quad i = 1, \dots, n$$

i) As an important check calculation the individual residuals v_i also may be calculated by substitution of the parameters x into the observation equations:

$$v = B \cdot \Delta x + T .$$

ii)

$$\left[\frac{B_{ij} v_i}{g_{ii}} \right] = 0 \quad \text{for all } j = 1, \dots, u.$$

iii) The minimum (least squares) is found by the equation

$$M = (B^T G^{-1} T)^T \Delta X + T^T G^{-1} T ,$$

and is compared as a check calculation with

$$M = \left[\frac{v_i v_i}{g_{ii}} \right] ,$$

calculated from individual residuals v_i .

4. INVESTIGATION OF PRECISION

4.1 A posteriori Variance factor

An a posteriori estimate $\overline{S^2}$ for the variance factor may be obtained from the minimum M :

$$\overline{S^2} = \frac{M}{r}$$

The null hypothesis that both variance factors (a priori and a posteriori) belong to the same population, can be tested using the F-distribution. If the variance ratio

$$\frac{\overline{S^2}}{S^2} < F_{(1-\alpha, r_1, r_2)},$$

the null hypothesis has to be accepted at the α significance level, and for r_1 and r_2 as the number of degrees of freedom used in determining $\overline{S^2}$ and S^2 respectively.

4.2 Precision of adjusted parameters

An estimate of the variance-covariance matrix of the adjusted parameters (S_x) is found by application of the general law of propagation of variances as:

$$(S_x) = S^2 Q_{xx},$$

where the cofactor matrix Q_{xx} is the inverse of N :

$$Q_{xx} = N^{-1}.$$

5. OBSERVATION EQUATIONS FOR A CONTROL NETWORK

i) Direction from station P to station Q, D_{PQ} :

$$P \text{ to } Q : v_D = a_{PQ} dN_P + b_{PQ} dE_P - a_{PQ} dN_Q - b_{PQ} dE_Q - dO_P + T_D$$

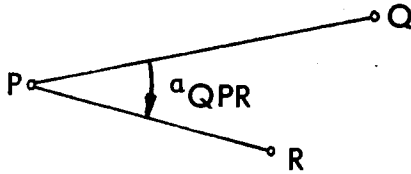
$$T_D = \theta_{PQ} - (D_{PQ} + \overline{O}_P)$$

ii) Distance between stations P and Q, d_{PQ} :

$$P \text{ to } Q: v_d = -\cos \theta_{PQ} dN_P - \sin \theta_{PQ} dE_P + \cos \theta_{PQ} dN_Q + \sin \theta_{PQ} dE_Q + T_d$$

$$T_d = d_{PQ}^{calc.} - d_{PQ}^{observ.}$$

iii) Angle at station P between stations Q and R, α_{QPR} :



$$v_{\alpha} = (a_{PR} - a_{PQ}) dN_P + (b_{PR} - b_{PQ}) dE_P + a_{PQ} dN_Q + b_{PQ} dE_Q \\ - a_{PR} dN_R - b_{PR} dE_R + l_{\alpha}$$

$$l_{\alpha} = (\theta_{PR} - \theta_{PQ}) - \alpha_{QPR}$$

NOTATION

For these observation equations the following notation has been adopted:

\bar{E} , \bar{N} : are approximate coordinates of stations

dE , dN : are the least squares parameters for the unknown coordinates

$$E = \bar{E} + dE , \text{ and}$$

$$N = \bar{N} + dN : \text{ are the adjusted final coordinates}$$

\bar{O}_P : is the approximate orientation of the direction observations at station P, with respect to the coordinate system.

dO_P : is the least squares parameter for the orientation at station P.

$O_P = \bar{O}_P + dO_P$: is the adjusted final orientation at station P.

D , d , α : are the observed values for direction, distance and angle respectively.

v_D , d_d , v_{α} : are the corrections (residuals) to these observed values

T_D , T_d , T_{α} : are the absolute terms

θ , S : are the preliminary bearing and distance, calculated from approximate coordinates \bar{E} , \bar{N} .

a , b : are the direction coefficients, calculated according to the equations

$$a_{PQ} = \frac{\rho'' \sin \theta_{PQ}}{S_{PQ}} , \quad b_{PQ} = -\frac{\rho'' \cos \theta_{PQ}}{S_{PQ}}$$

$$\rho'' = 206\,264.81''$$

Attention: Dimensions.

6. CALCULATION OF POINT ERROR ELLIPSES

The weight coefficient Q_{xx} of the adjusted parameters dN_i , dE_i and dO_i is of the general form:

$$Q_{xx} = \begin{bmatrix} Q_{N_1N_1} & Q_{N_1E_1} & \dots & \dots & \dots \\ Q_{E_1N_1} & Q_{E_1E_1} & & & \\ \cdot & & Q_{N_iN_i} & Q_{N_iE_i} & \cdot \\ \cdot & & Q_{E_iN_i} & Q_{E_iE_i} & \cdot \\ \cdot & & \cdot & \cdot & \cdot \\ \cdot & & \cdot & \cdot & Q_{O_jO_j} \end{bmatrix}$$

The basic parameters of the error ellipse at the station i are calculated from the following equations:

i) The a priori variance factor S^2

ii) The eigen values $\lambda_{1,2}$ of the cofactor matrix for the station i :

$$\lambda_{1,2} = \frac{1}{2}(Q_{N_iN_i} + Q_{E_iE_i}) \pm \frac{1}{2}\sqrt{(Q_{N_iN_i} - Q_{E_iE_i})^2 + 4Q_{N_iE_i}^2}$$

(positive sign for λ_1)

iii) Semi major and minor axis of the point error ellipse:

$$\text{Semi major axis : } \sqrt{S^2 \lambda_1}$$

$$\text{Semi minor axis : } \sqrt{S^2 \lambda_2}$$

iv) Orientation of semi major axis θ_i :

$$\theta_i = \frac{1}{2} \arctan \frac{2 \cdot Q_{N_iE_i}}{Q_{N_iN_i} - Q_{E_iE_i}}$$

DIRECTION

OBSERVATIONS

STATION Alpha	DATE	1/4/55	WEATHER	Clear	OBSERVER	J. Jones
	TIME	1600 to 1700			BOOKER	W. Smith

ARC STATION	F.L.	F.R.	DIFF "	MEAN	RED. MEAN	q	V	VV	COMMENTS
BETA	0 00 05	180 00 22	+17	0 00 13.5	0 00 00	0.00	+0.17	0.03	
GAMMA	74 39 55	254 40 19	+24	74 40 07.0	74 39 53.5	1.62	1.79	3.20	
DELTA	99 01 04	279 01 19	+15	99 01 11.5	99 00 58.0	-2.12	-1.95	3.80	
							-0.50	+0.01	
BETA	45 02 29	225 02 52	+23	45 02 40.5	0 00 00	0.00	-0.50	0.25	
GAMMA	119 42 22	319 42 42	+20	119 42 32.0	74 39 51.5	-0.38	-0.88	0.77	
DELTA	144 03 32	364 03 53	+21	144 03 42.5	99 01 02.0	+1.88	+1.38	1.90	
							+1.50	0.00	
BETA	90 04 57	270 05 18	+21	90 05 07.5	0 00 00	0.00	0.00	0.00	
GAMMA	164 44 49	344 45 09	+20	164 44 59.0	74 39 51.5	-0.38	-0.38	0.14	
DELTA	189 06 00	9 06 16	+16	189 06 08.0	99 01 00.5	+0.38	+0.38	0.14	
							0.00	0.00	
BETA	135 07 28	315 07 42	+14	135 07 35.0	0 00 00	0.00	-0.25	0.06	
GAMMA	209 47 21	29 47 31	+10	209 47 26.0	74 39 51.0	+0.88	+0.63	0.40	
DELTA	234 08 26	54 08 44	+18	234 08 35.0	99 01 00.0	-0.12	-0.37	0.14	
							+0.76	+0.01	10.85
GRAND MEANS									
BETA		0 00 00		$S_{SD}^2 = \frac{10.85}{6} = 1.81$				$S_{GM}^2 = \frac{1.81}{4} = 0.45$	
GAMMA		74 39 51.88							
DELTA		99 01 00.12							

$\therefore S_{SD} = \pm 1.35"$ $S_{GM} = \pm 0.67"$

n = No. of Arcs i = 1, n
 k = No. of Stations .. j = 1, k
 $q_{ij} = (\text{Red. Mean})_{ij} - (\text{Grand Mean})_j$
 $V = q_{ij} - \frac{\sum_{j=1}^k q_{ij}}{k}$

VARIANCE ESTIMATES.
 single direction
 $S_{SD}^2 = \frac{[VV]}{(n-1)(k-1)}$

grand mean direction
 $S_{GM}^2 = \frac{S_{SD}^2}{n}$

B.7

ZENITH DISTANCE MEASUREMENT (3 HAIR TECHNIQUE)

Station: <u>Pillar 6 G.A.S</u>				Observer: <u>G.J. Bowler</u>		
Height of Instrument: <u>0.251 m</u>				Instrument: <u>Wild T2 S/N° 22940</u>		
Target: <u>T.S. 103</u>				Date: <u>21st October 1986</u>		
Height of Target: <u>Top of Pillar</u>				Time: <u>0910^{hrs}</u>		
				Weather: <u>Sunny No Wind</u>		
Set	Hair	Face	Vertical Circle Reading	Zenith Distance $z = \frac{1}{2}(360 + L - R)$	v	Error Calculation
	Upper	Left	<u>86 29 30</u>	$z_u: 86 11 55.0$	+0.17	$\Sigma v^2 = 0.17$
		Right	<u>274 05 40</u>			
		360+L-R	<u>172 23 50</u>			
	Centre	Left	<u>86 12 20</u>	$z_c: 86 11 55.0$	+0.17	$s_z = \sqrt{\frac{\Sigma v^2}{2}}$ $= \pm 0.29''$
		Right	<u>273 48 30</u>			
		360+L-R	<u>172 23 50</u>			
	Lower	Left	<u>85 55 05</u>	$z_l: 86 11 55.5$	-0.33	$s_z = \frac{s}{\sqrt{3}}$
		Right	<u>273 31 14</u>			
		360+L-R	<u>172 23 51</u>			
Mean Zenith Distance				$\bar{z}: 86 11 55.17$	$\left[\frac{v}{0} \right]$	$= \pm 0.17''$
Remarks:						

Station: <u>Pillar 6 G.A.S</u>				Observer: <u>G.J. Bowler</u>		
Height of Instrument: <u>0.251 m</u>				Instrument: <u>Wild T2 S/N° 22940</u>		
Target: <u>T.S. 103</u>				Date: <u>21st October 1986</u>		
Height of Targets: <u>Top of Pillar</u>				Time: <u>0920^{hrs}</u>		
				Weather: <u>Sunny N° Wind</u>		
Set	Hair	Face	Vertical Circle Reading	Zenith Distance $z = \frac{1}{2}(360 + L - R)$	v	Error Calculation
	Upper	Left	<u>86 29 29</u>	$z_u: 86 11 53.0$	+0.17	$\Sigma v^2 = 1.17$
		Right	<u>274 05 43</u>			
		360+L-R	<u>172 23 46</u>			
	Centre	Left	<u>86 12 16</u>	$z_c: 86 11 54.0$	-0.83	$s_z = \sqrt{\frac{\Sigma v^2}{2}}$ $= \pm 0.76''$
		Right	<u>273 48 28</u>			
		360+L-R	<u>172 23 48</u>			
	Lower	Left	<u>85 55 04</u>	$z_l: 86 11 52.5$	+0.67	$s_z = \frac{s}{\sqrt{3}}$
		Right	<u>273 31 19</u>			
		360+L-R	<u>172 23 45</u>			
Mean Zenith Distance				$\bar{z}: 86 11 53.17$	$\left[\frac{v}{0} \right]$	$= \pm 0.44''$
Remarks:						

APPENDIX C1

Photogrammetric Control

The following sketches illustrate a selection of suitable and unsuitable points to be considered during photo-identification for planimetric and height control. They should be used as a general guide only, as the selection of suitable points will depend on the photo scale. For small scale photography points marked "Bad" in these sketches may prove to be satisfactory.

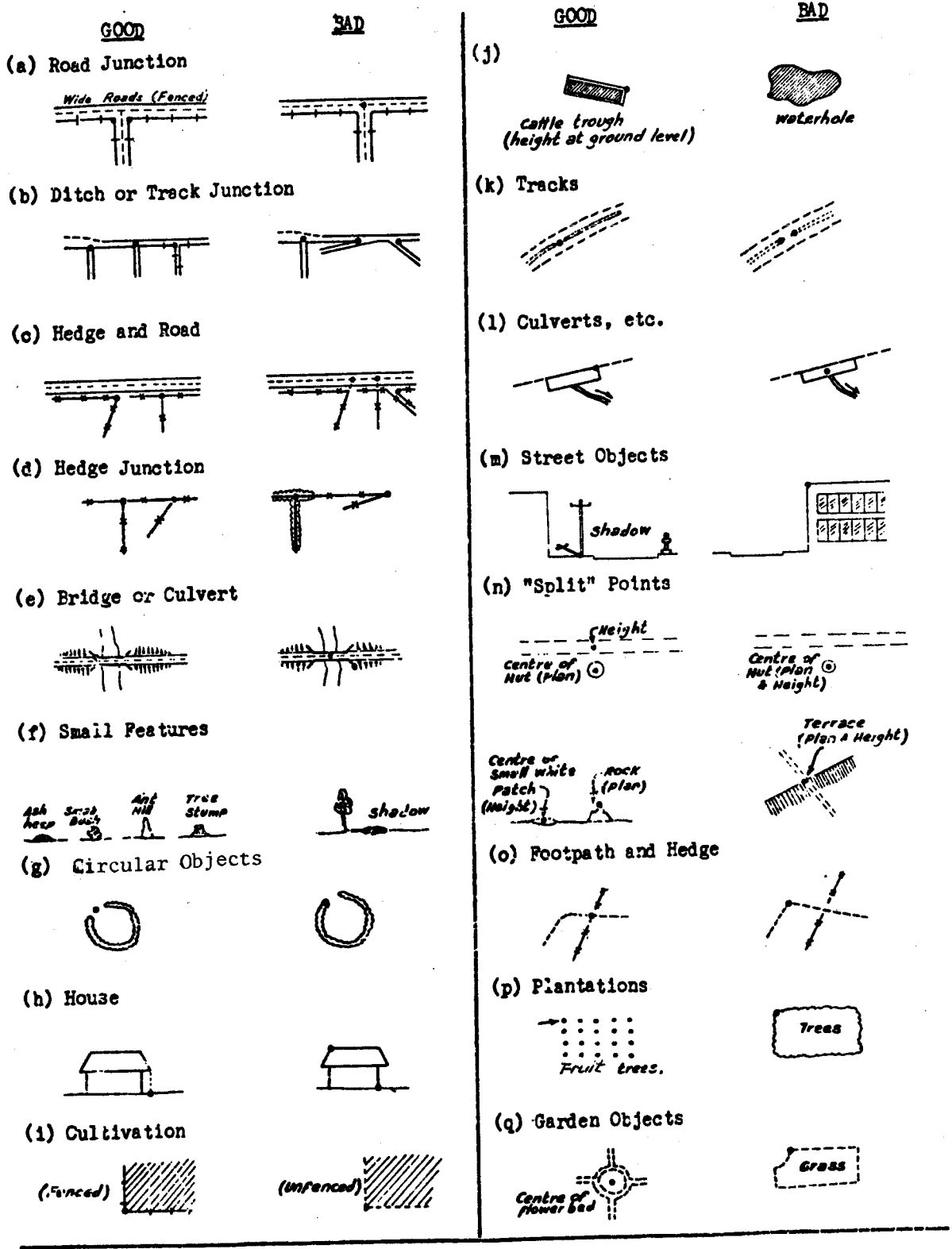
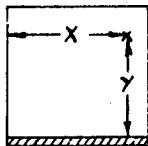
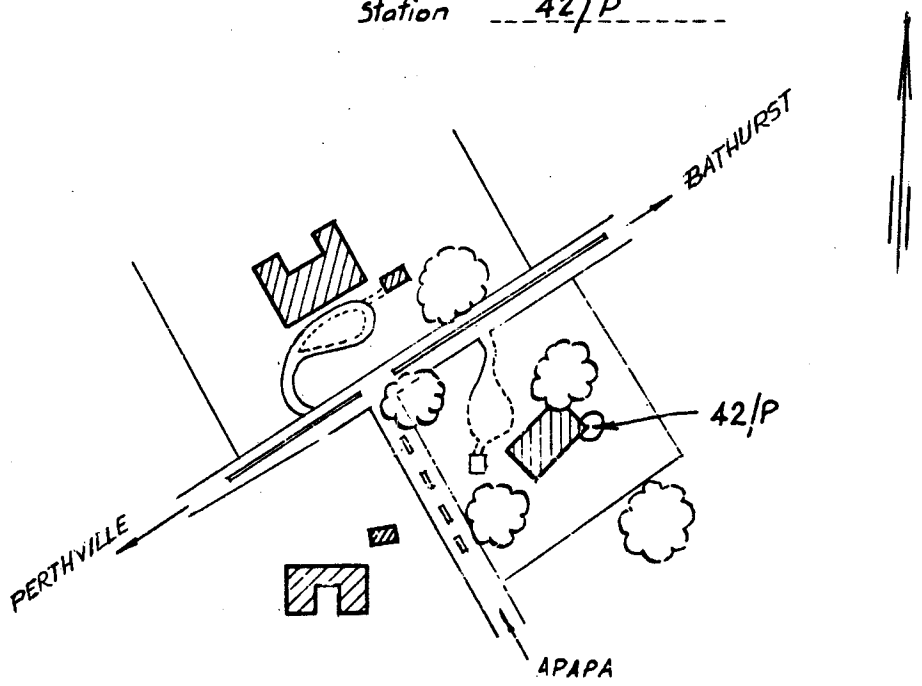


PHOTO POINT DESCRIPTION
SPECIMEN

Survey: BATHURST 1:10.000
Job no. 1961/2

Page 7

Station 42/P



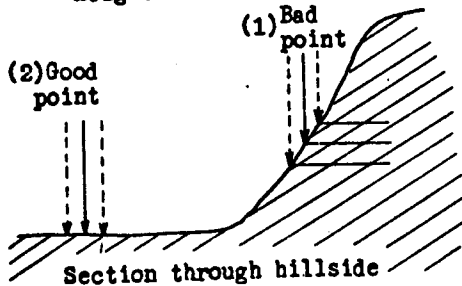
Circled on photograph no. 261
Photograph co-ordinates X 17.8 mm
Y 18.4 mm

Description of mark: Corner of house
Location of station: S.E. Corner of house south of BATHURST-PERTHVILLE Road

Co-ordinates: E 364 210.71 Drawn by E.X. PERT.
N 241 365.81 Date 3-6-61

Height: _____
Signed O.B. SERVER

Height Control:-



It can be seen clearly that any slight error in field identification or in placing the floating mark during the plotting process, will cause considerable height error in (1), but will have no appreciable effect in (2).

APPENDIX D

Cadastral Project

PURPOSE

The assumed purpose of the survey is for a primary application to convert land held under the old system title to a Torrens title, i.e. to bring the land under the provisions of the Real Property Act. This survey should include not only the land held under the old system title but also any easements that may be appurtenant to the land.

BACKGROUND

The properties you will survey are adjacent to Karingal Camp. They have not been surveyed recently. As an example of the land that you will survey, the camp site is part of POR. 38 Parish of Bathurst originally granted to William Lane and known as Orton Park. This land is described in the conveyance no. 248 Book 2594 which is based in part on the survey made by Mr. Surveyor Bayliss on the 10th September, 1959.

Please note the reference to easements which form part of the title.

Regarding your particular land, a number of other surveys defining the lots surrounding the land survey all have a bearing on the redefinition of the boundary of the subject land.

Copies of the most important documents will be issued to students at the survey camp. Other plans of lesser importance, which nevertheless should still be examined, will also be available but just for your inspection.

BASIC CONSIDERATIONS

The Cadastral Survey Exercise is not calculated on ISG. The survey and resulting plan are carried out and prepared to the requirements of the SURVEY PRACTICE REGULATIONS and the Registrar General's Office. The survey is carried out assuming it is in a Proclaimed Survey Area.

A number of considerations will determine what survey information is most necessary and what boundary adoptions should be made.

- (1) Where the land is surrounded by other old system land, attention should be given to the position and age of existing occupations as this will help to indicate the position of the boundaries as originally surveyed.
- (2) Where the land is surrounded by land held under Torrens title, greatest consideration should be given to preserving those titles, the balance then going to the land which is the subject of the primary application. If substantial differences with occupations exist, consideration would need to be given to an application based on adverse possession.
- (3) When the land in question has been the subject of a previous survey or surveys that have been accepted by the Land Titles Office, greatest weight should be given to any marks established or monuments fixed under those previous surveys.

D.2

- (4) Where a number of previous surveys relating to the same boundaries are in existence, some minor disagreement in dimensions will usually be found. While always considering the pre-eminence of marks (where by measurement they can be shown not to have moved), the survey that has redefined the boundaries by interpolation from surrounding information, as compared to one which has extrapolated from information to the subject land, should be given greatest weight.
- (5) In most surveys, the road alignment (if any) should be given particular consideration. This alignment should be such that sufficient dimensions exist between it and the boundaries forming the opposite side of the road.
- (6) When examining the primary application, the Land Titles Office is only concerned with the re-established external boundaries of the land in question (and in the position of any easements) and not with the position of any internal boundaries created by parcels that are part of the total application. There must be a one to one relationship between the parcel of land and easements defined by survey and the ensuing title that issues.

SURVEY HINTS AND REQUIREMENTS

- (1) The traverse legs which form the framework from which the boundary evidence is measured should, where possible, clearly parallel the occupation. Long radiations from instrument stations to pegs, corner posts, etc., should be kept to a minimum.
- (2) All marks measured from the basic traverse framework must have in addition at least one redundant measurement for checking purposes. Note that whilst the traverse surround can be checked by closure, the measurements to any marks connected to this traverse by radiation or offset are not checked as part of the total closure.
- (3) Where short boundaries are traversed, an extended backsight should be provided for the transfer of azimuth to the subsequent traverse leg.
- (4) The bearings and distances shown on any old plans that are to be utilised in the survey must be checked by calculation prior to any final adopted boundaries being determined. Errors in old plans are not without precedent.
- (5) Measurements to, and description of, occupation (particularly corner posts) should be made, as these can act in future years as monuments. Measurements are usually made to the centre base of the post, the position of which should be projected onto the top or face of the post. Where the centre base obviously does not represent the true corner position, the intersection of the line of fences can be taken.
- (6) Field notes should be clear and concise, indicating all measurements and the sketched relationships between all marks measured. Information must be immediately entered into the field book. All pages should be cross-referenced, indexed, refer to a master diagram, be signed and dated by the group and the supervisor.

D.3

- (7) All surveys shall be made in accordance with the Survey Practice Regulations.

See ss 8-13 Survey Practice
 s 21 Country Surveys
 ss 25-29 Redetermination of Boundaries
 ss 41, 42A-44 Accuracy
 ss 47-48, 50-53 Field Notes
 ss 54-57 Plans

Reference should also be made to the N.S.W. Crown Lands Office Survey Directions, 1981.

- (8) Check all equipment before commencing survey. In particular, check the operation of your particular EDM instrument and that each tribrach is in adjustment. You are required to standardise your steel band with a nominated baseline, located at Mitchell College. (Sec D7)
- (9) Traverse closures and adjusted coordinates, in a nominated system, of boundary corners should be approved by the supervisor before traverse marks are removed.
- (10) Every mark shown on a plan which refers to the boundaries of the subject property must be shown as either "found", "found (disturbed)", or "gone".
- (12) You will be required to calculate radiations to nominated "missing" corners on the area under survey.

SUBMISSIONS

The report is to be a group submission, comprising:

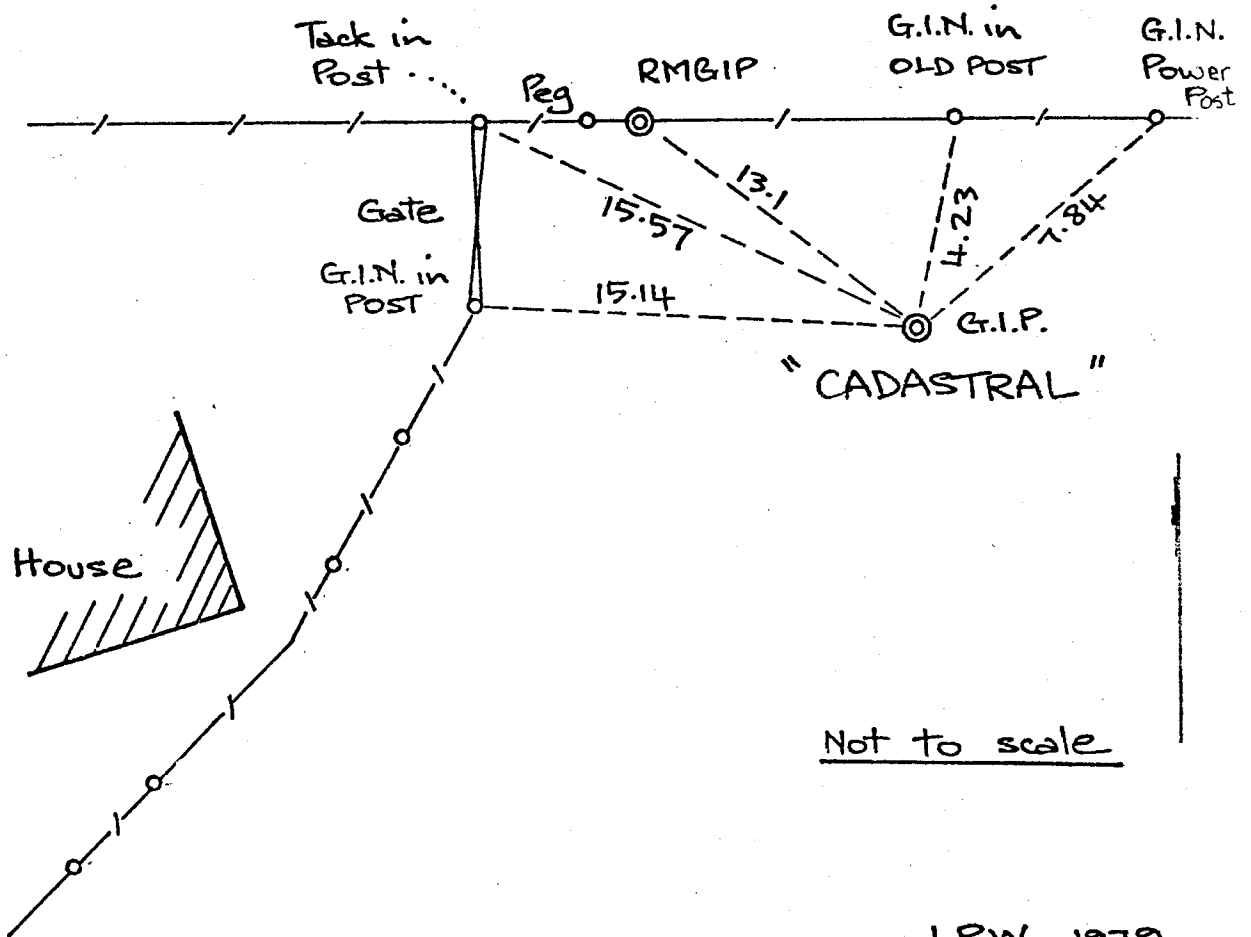
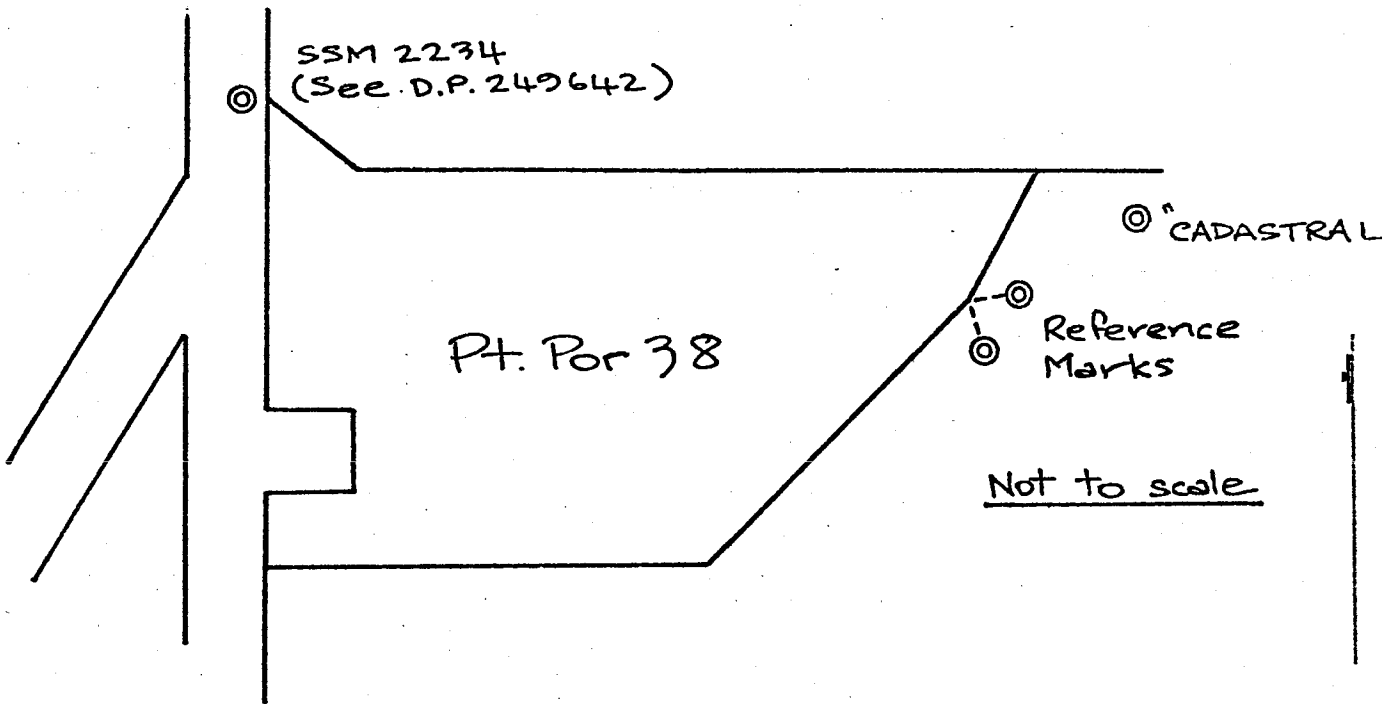
- (1) Field notes - final adjusted bearings and distances of all observations must be shown in the field notes, preferably in a different colour.
- (2) Calculations and report - this will include the traverse misclosures and adjustments, the calculation of boundaries, the comparisons, the coordination of the boundaries and the work sheet.
- (3) A brief report including the following aspects relating to the survey:
 - (a) method of survey
 - (b) any problems in interpreting the old system description or any of the plans of survey
 - (c) a discussion on any differences between various plans of survey and the measured values

D.4

- (d) the method of fixation of boundaries and any problems confronted in the boundary definition. Discuss each boundary separately.
- (e) A neat sketch of survey is to be submitted. It should contain such complete information that a survey draftsman could compile a plan suitable for submission to the Land Titles Officer from it. It should include parcel identifiers of the parcel under survey as well as for adjacent parcels.

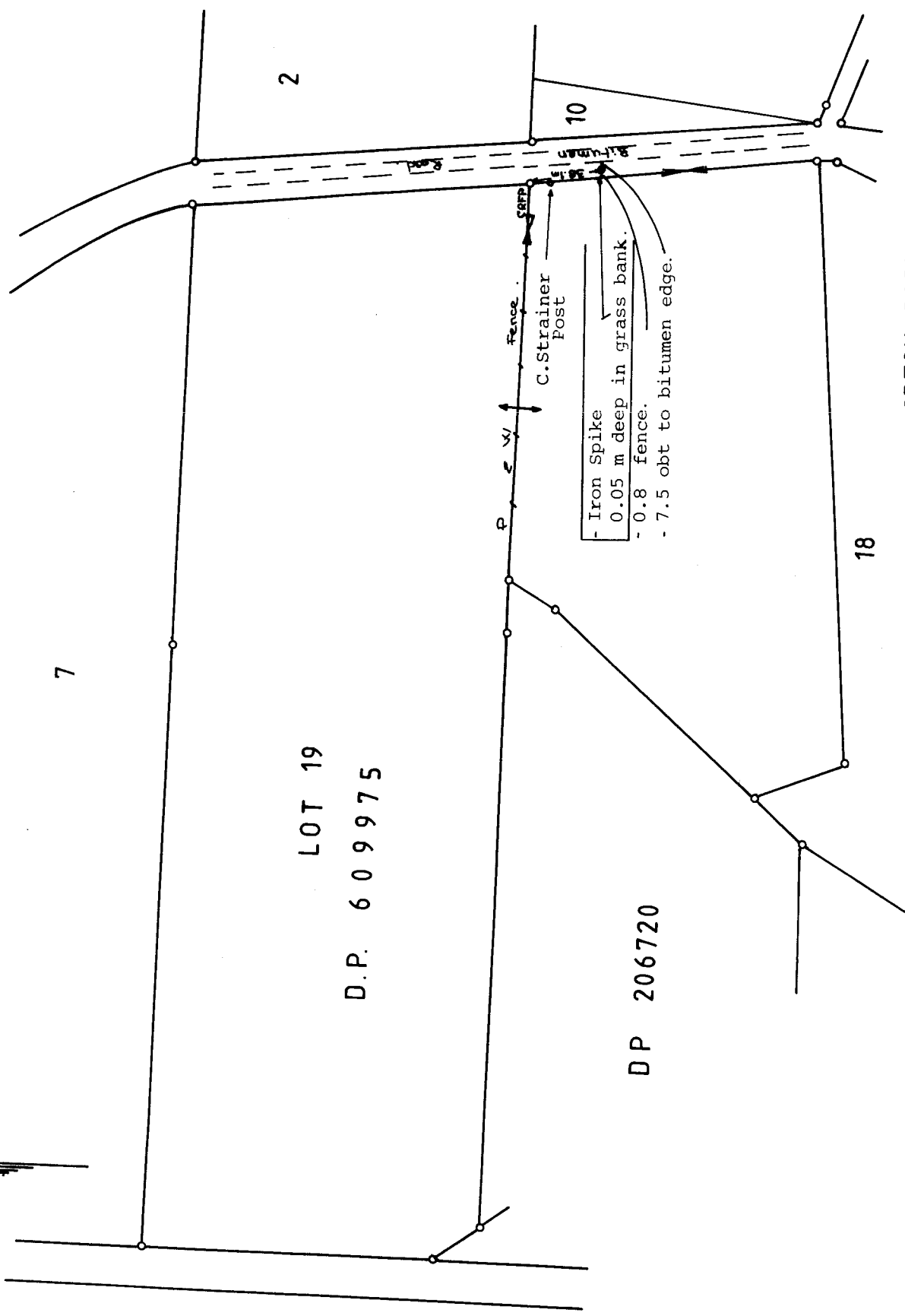
D.5.

CONTROL and REFERENCE MARKS
for CADASTRAL EXERCISE



CADASTRAL 2

D6

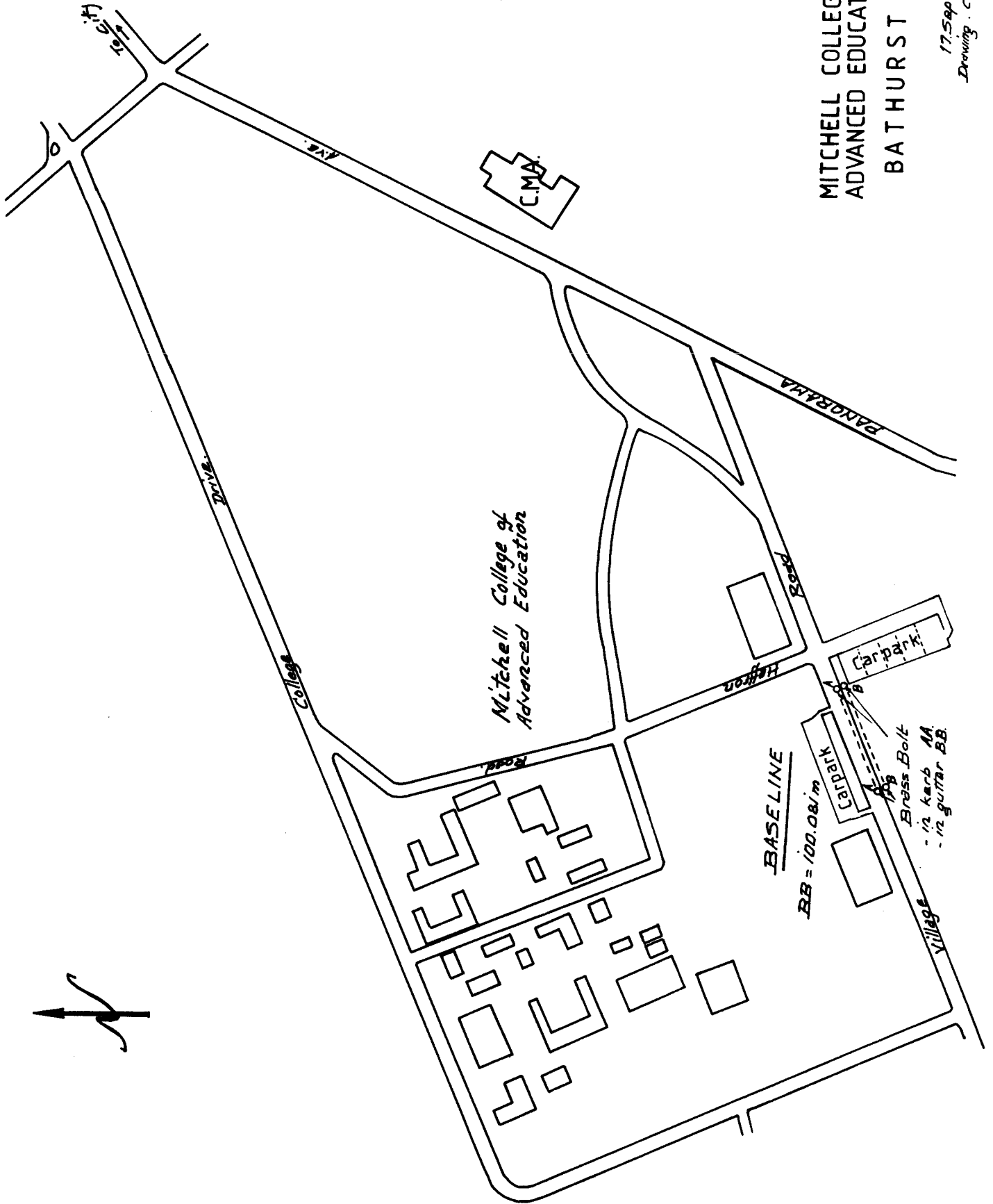


ORTON PARK - BATHURST

SEP. 1984.

DRAWING. C. RUSU

D7



MITCHELL COLLEGE of
 ADVANCED EDUCATION.
 BATHURST

17.5.90. 1984
 Drawing: C. RUSSELL

APPENDIX E

Bathurst Land Use Survey

AIM AND SCOPE

The aim and scope of the land use survey is for each group of three students to undertake a survey in the environs of Bathurst. In making this survey, both field sampling and air photograph interpretation techniques will be employed. The final result will be a coded and symbolised map showing the land use of an area about one stereomodel in extent.

SCENARIO

This type of survey could well be undertaken to provide land use information for a local government authority or a land information system. Other information within that system could be the legal description, coordinates, rate and valuation information, soil information and census data. The smallest unit or reference for these types of systems is usually the land parcel. Therefore, we require the land use survey in this exercise to be property based. Accordingly, in this exercise, make your land use decision based on the most predominant use within the properties' boundaries as portrayed on the scale 1:25 000 map, as far as possible.

METHOD

Each group will produce a land use map of the area covered by one stereopair of the aerial photographs of the scale 1:20 000 photography. The task will entail three distinct stages:

- (1) Air photograph selection of representative areas
- (2) Ground inspection and interpretation of those selected areas
- (3) Air photograph interpretation based on the ground inspected areas

STAGE 1

Selection of Representative Areas:

This stage will be carried out at base, using mirror stereoscopes. Time involved should be about 2 hours. The aim of this stage is to select areas, which appear to represent many similar areas in the model, suitable for ground inspection. These areas will become the key to the whole survey.

This selection will be carried out by, firstly, broadly classifying the land patterns over the whole model according to the photographic TONE, TEXTURE and PATTERN, and secondly, by picking out 2 or 3 areas in each class with suitable road access for easy ground inspection.

To achieve these ends, a systematic inspection of the model under the mirror stereoscope will be made. Evolve a simple classification system based on the tone, texture and pattern of the photograph - whether an area is light or dark, or has a rough or smooth appearance. The whole model should be classified according to your system. A suggested classification system for your black and white photography may be:

E.2

- 3 Tones - light, medium dark
- 2 Textures - rough, smooth
- 2 Patterns - no, yes

This information should be recorded on an overlay to one of the black and white photographs. This classification system should not be based on land use, but on the appearance it has in the photograph. At this stage, inspect the colour prints that will be available for any additional or conflicting information that may be evident. On completion of this classification over the whole model, select two to three areas in each class suitable for ground inspection. In contemplating this, remember that you will not be able to venture onto private property. The total number selected should be between 15-20 representative areas, preferably with some of differing classes being adjacent to each other, to reduce travelling time.

STAGE 2

Ground Inspection and Land Use Interpretation of Selected Areas:

In this stage, the TONE, TEXTURE and PATTERN classification will be matched with the Land Use categories (as listed on last page of this Appendix). Time involved in the field should be about three hours.

Upon reaching the site of the selected area, make a brief note of the activity carried out on the land (in excess of the land use category) and re-inspect the aerial photography.

Decide into which category this land should be placed.

STAGE 3

Air Photo Interpretation:

Armed with the "ground truth" information gathered from Stages 1 and 2, you are now in a position to carry out a land use survey. Using the mirror stereoscope, re-examine the whole model making land use decisions under the categories listed. The information should be recorded on a map dyeline using the appropriate code and a land use decision made for each property/portion as delineated on the scale 1:25 000 map. Where the property does not appear on the map, note the land use regardless of this handicap. Finally, on this map or on another dyeline, show the land use by colours. This is a map and therefore it will need a key, a date, title, who surveyed it, methods used and the location of the survey, to be shown.

SUBMISSION

This whole exercise is a GROUP EXERCISE, including the REPORT.

1. Overlay to the photograph showing the TONE/TEXTURE/PATTERN classification from Stage 1 as well as portraying the actual sites visited on the ground.

E.3

2. The "field notes" of the visits to the selected sites, stating the actual land use at each site and any immediate implications of your findings on the ground.
3. The Land Use map showing the land coded in both numbers and colours. This may be completed on one or two separate maps, as you wish.
4. A report of about 2 pages in length that should include the following considerations: brief introduction giving methods used and any problems encountered; suggestions for improvements to the methods used; a brief description as to how your group would organise a land use survey over the whole of the Bathurst/Orange area. Would different types of aerial photography flown at a chosen time of year assist in this task? General comments and conclusions.

CODES FOR THE BATHURST LAND USE SURVEY

Code No.	Attribute/or Class/or Sub-Class	Colour or Symbol
1	Non-urban (rural)	
1.1	under cultivation (crops except grass)	brown
1.12	cereals	light brown
1.14	vegetables/flowers/vines	brown
1.16	orchard	brown stripes
1.2	forest (including scrub)	green
1.22	plantations (cultivated)	lime green
1.24	natural	dark green
1.242	dense timber	green & label (D)
1.244	open (scattered) timber	green & label (O)
1.26	scrub	very light green
1.3	pasture (grazing)	yellow
1.32	improved	light yellow
1.34	natural	yellow
1.4	water	blue
1.42	man-made	light blue
1.44	natural	dark blue
1.46	swamp	dark blue & label (S)
1.5	unused/unclass/waste	blank (white)
1.6	intensive animal production	purple stripes
1.62	poultry sheds, pigs	purple stripes & label (P)
1.64	stud yards, lot feed cattle	purple stripes & label (S)
1.7	mining and quarrying	purple & label (Q)
2	Residential (urban)	light red
3	Business (urban)	red
4	Industrial (urban)	purple
5	Special Uses Label accordingly, e.g. school, hospital, church and parking	light grey
6	Open Space (recreation)	
6.1	passive	green stripes & label (P)
6.2	active	green stripes & label (A)
7	Roads	black line
7.1	bitumen	black line & label (B)
7.2	loose metal	black line & label (M)

APPENDIX F

Constants of EDM Instruments

INSTRUMENT	SERIAL NUMBER	ADD. CONST.	σ ADD CONST.	DATE OF CALIBRATION	REFLECTOR TO WITH ADD. CONST. REFERS
AGA 14	14075	-4mm	± 0.9 mm	15.8.81	New AGA
HP 3800B	1141A00110	-1mm	± 0.6 mm	7.78	HP/01d AGA
HP 3800B	1226A00368	+1mm	± 0.5 mm	7.78	HP/01d AGA
HP 3805A	1338A00123	-2mm	± 0.7 mm	23.4.83	HP/01d AGA
HP 3805A	1440A01439	+3mm	± 0.4 mm	4.6.81	HP/01d AGA
HP 3820A	1650A00131	-1mm	± 1.5 mm	23.4.83	HP/01d AGA
KERN DM501	250942	(SEE NEXT PAGE)			KERN
TELLUROMETER CA 1000	6249-E, 6250-E	-23m	± 11 mm	16.8.80	N.A.
TOPCON DM-C2	911266	+4mm	± 0.4 mm	9.8.80	New AGA
TOPCON GTS-2	B45056	+1mm*	± 0.2 mm	20.10.83	Topcon
PENTAX PX-06D	532238	+0mm**	± 0.3 mm	1.9.86	01d AGA
NIKON NID-3	310444	+5mm***	± 0.4 mm	1.9.86	01d AGA
SOKKISHA SDM-3ER	76359	+1mm****	± 0.5 mm	25.8.86	01d AGA

* Internal additive constant setting = -07 (mm). As for tiltable TOPCON prism (in triple prism holder).

** Reflector constant set to '30' and instrument correction to '-44'.

*** Reflector constant set to '0.030' and instrument constant to '37'.

**** Reflector constant set to '30'.

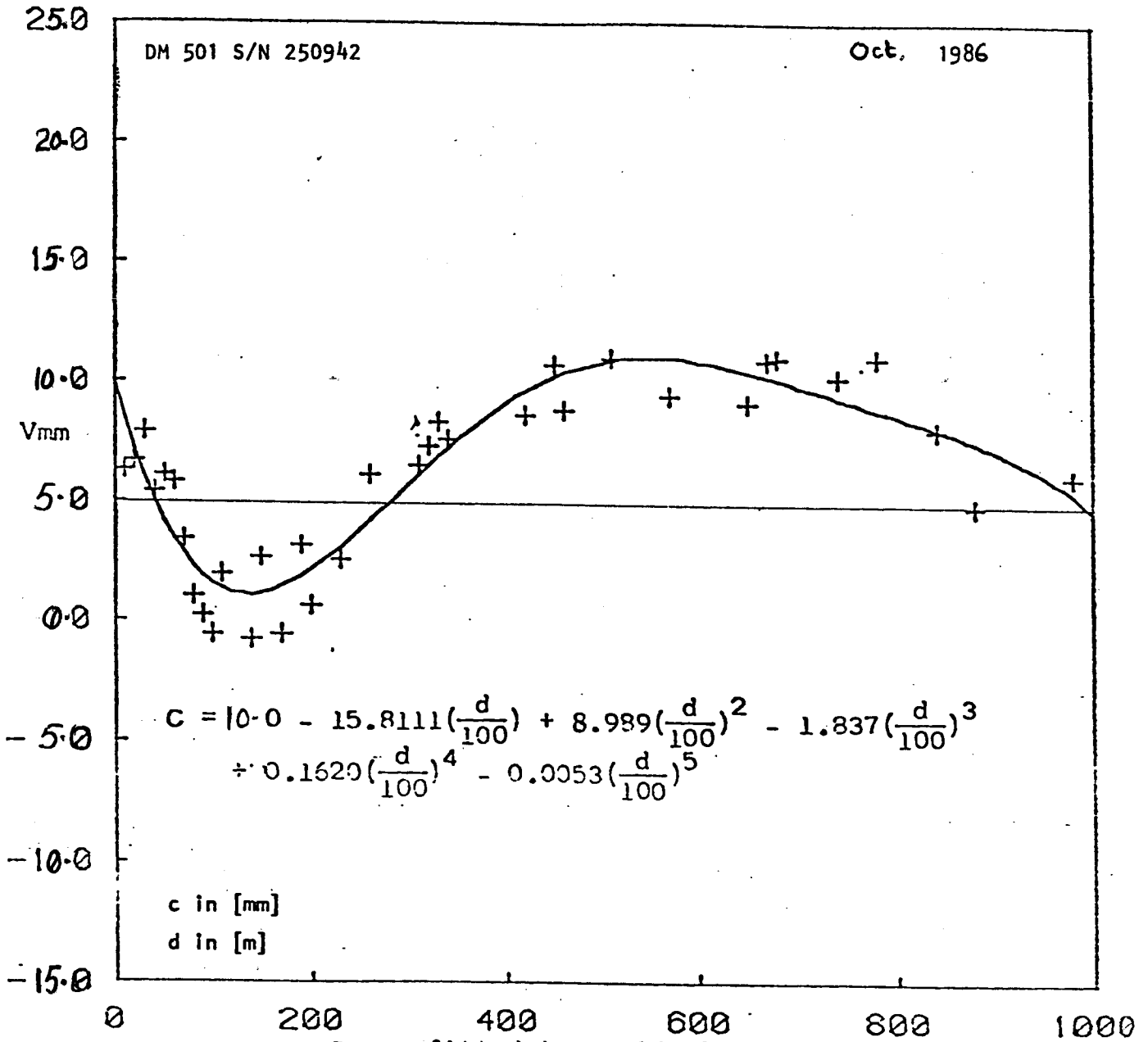
F.2

INSTRUMENT CORRECTION FOR DM 501:

+ EITHER: SCALE OFF DIAGRAM BELOW OR COMPUTE FROM EQ. USING ALL TERMS:

DISTANCES < 100 m → CLOSED DIAPHRAGM

> 100 m → OPEN DIAPHRAGM



Curve fitted to residuals from Regents

Park and 100m Baseline. (Valid with built-in constant '999.058'.)

ADDITIVE CONSTANTS OF BAROMETERS

MANUFACTURER	SERIAL NO.	CONSTANT ON				
		18.2.80	27.1.81	8-11.2.83	3-7.2.84	11-22.7.86
Mechanism	271/61	+4.0mm	+4.2mm	+4.2mm	+4.2mm	+4.0mm
"	302/62	-3.2mm	-3.4mm	-3.6mm	-3.5mm	-3.0mm
"	655/65	-3.7mm	-3.4mm	-3.7mm	-3.6mm	-3.6mm
"	656/65	-2.0mm	-1.8mm	-1.9mm	-1.8mm	-1.7mm
"	657/65	-2.3mm	-2.2mm	-2.2mm	-2.2mm	-2.3mm
Thommen (large)	25294	-6.4mb	-6.3mb	-2.1mb	-2.0mb	-2.1mb
"	234619	-2.0mb	-1.9mb	...mb*	+6.0mb	-2.3mb
"	235745	-2.1mb	-3.3mb	-4.2mb	-4.5mb	-5.0mb
"	220459	+1.1mb	-2.0mb	-2.2mb	-2.2mb	-0.6mb
Dobbie	685	-0.02 inch	-	-	-	-
"	2531	-0.04 inch	-	-	-	-
"	688	-0.03 inch	-	-	-	-
"	686	+0.03 inch	-	-	-	-
Watts	2836	-	-	-	-	-
Dobbie	691	+0.06 inch	-	-	-	-
Esdäile	52/155	-0.03 inch	-	-	-	-

11.7.80

Thommen (small)	416441	-0.4mb	-3.1mb	-5.8mb	-4.5mb	-3.3mb
"	416452	+0.6mb	-3.3mb	-7.0mb	-16.4mb	-15.7mb
"	417701	+0.2mb	-2.2mb	-17.6mb	-17.9mb	-16.9mb
"	417728	+0.1mb	+1.2mb	+0.3mb	+0.3mb	-1.2mb
"	418885	-	-3.6mb	-4.2mb	-4.2mb	+2.3mb
"	419048	±0.0mb	+0.5mb	+1.6mb	+0.8mb	-1.9mb
"	416394	+0.6mb	+0.6mb	-3.4mb	-3.3mb	-4.4mb

IMPORTANT: Use only the latest additive constants for the reduction of measurements.